Distributed Systems 1

CUCS Course 4113 https://systems.cs.columbia.edu/ds1-class/

Instructor: Roxana Geambasu

Large-Scale Software Systems Stacks

Lecture Theme

- We talked a lot about storage in this class, plus a bit about distributed computation. For storage, we focused on a particular type of interface (transactional databases).
- But there's a **vast range of infrastructural components** that are needed for building successful distributed applications. Large companies and open-source communities have such components available.
- This lecture aims to provide an index of such components.
 We won't give details about how these components are built, but pointers to where you can find out more.
- We'll also give pointers to valuable advice on skills and patterns useful for building large-scale systems.

Acknowledgements

- Because the course lecture is so broad, there's a lot to acknowledge for the content provided here.
- Particularly important for these slides are two sources:
 - A 2015 talk by Malte Schwarzkopf on software systems stacks at large companies [1].
 - A couple of talks by Jeff Dean about experience and advice from building some key infrastructure systems at Google (original slides [2] and [3]).

"What It Takes to Build Google?"



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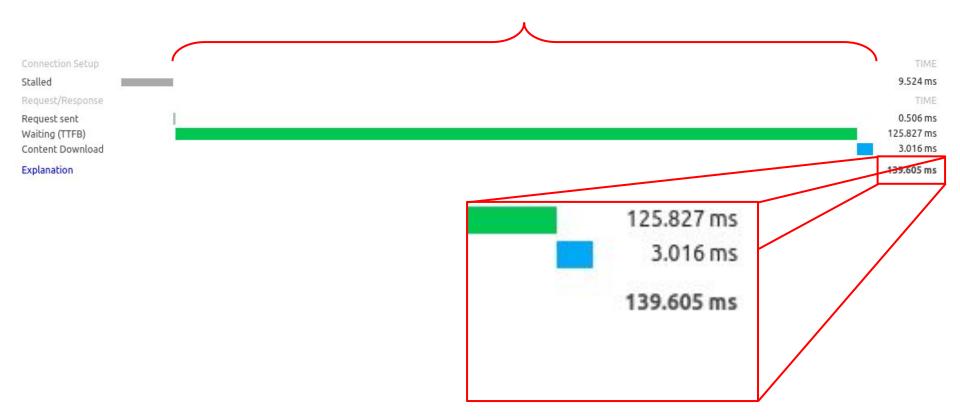


The University of Cambridge is a collegiate public research university in Cambridge, England. Founded in 1209, Cambridge is the second-oldest university in the English-speaking world and the world's fourth-oldest surviving university. Wikipedia

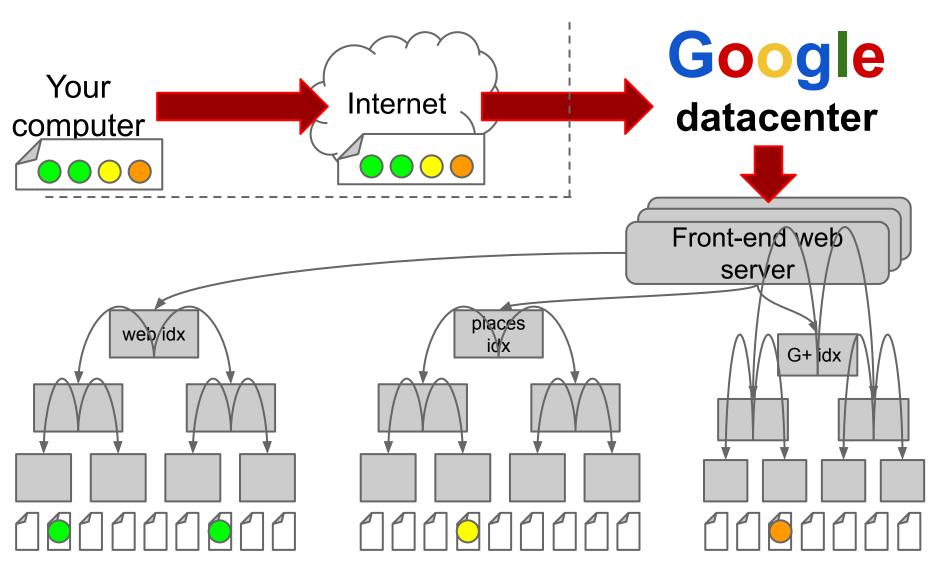
Address: The Old Schools, Trinity Ln, Cambridge CB2 1TN Motto: Hinc lucem et pocula sacra Acceptance rate: 20.8% (2013) Color: Cambridge Blue Founded: 1209, Cambridge Enrollment: 19,938 (2014)

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What happens here?



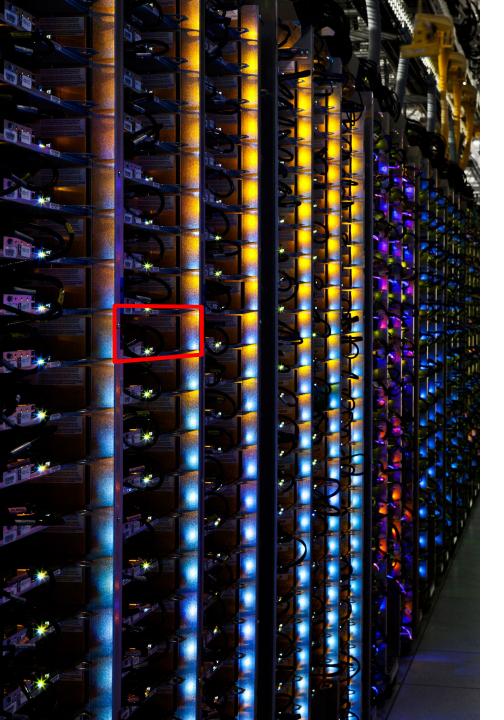
What happens in those 139ms?



What we'll chat about

- 1. Datacenter hardware
- 2. Cluster failures
- 3. Scalable & fault tolerant software stacks
 - a. Google
 - b. Facebook
 - c. Open source





From Meta (as of 2022):

- O(1M) machines in total
- O(10s) regions
- O(1000s) interdependent services
- "Machine"
 - no chassis
 - DC battery
 - mostly custom-made
- Network
 - ToR switch
 - multi-path core

A video surveying a Google Datacenter (as of 2020) is <u>here</u>.

The Joys of Real Hardware

Typical first year for a new cluster:

- ~0.5 overheating (power down most machines in <5 mins, ~1-2 days to recover)
- ~1 PDU failure (~500-1000 machines suddenly disappear, ~6 hours to come back)
- ~1 rack-move (plenty of warning, ~500-1000 machines powered down, ~6 hours)
- ~1 network rewiring (rolling ~5% of machines down over 2-day span)
- ~20 rack failures (40-80 machines instantly disappear, 1-6 hours to get back)
- ~5 racks go wonky (40-80 machines see 50% packetloss)
- ~8 network maintenances (4 might cause ~30-minute random connectivity losses)
- ~12 router reloads (takes out DNS and external vips for a couple minutes)
- ~3 router failures (have to immediately pull traffic for an hour)
- ~dozens of minor 30-second blips for dns
- ~1000 individual machine failures
- ~thousands of hard drive failures

(NB: Numbers are from 2007 Google study, but are most comprehensive in terms of class of failures. Other papers measure specific types of failure, such as <u>this</u> for disks and <u>this</u> for DRAM.)

Source: Jeff Dean

https://static.googleusercontent.com/media/research.google.com/en//people/jeff/stanford-295-talk.pdf, 2007.

Dealing with Scale and Failures

- 1. Leverage infrastructure systems that solve portions of your problem at scale and with fault-tolerance.
- 2. Follow engineering patterns for how to develop scalable, fault tolerant systems.
- Reason about the space of design and try make design choices based on assessments of tradeoffs, either from back-of-the-envelope or from basic prototype evaluations.

Today: We'll talk about the kinds of infrastructure systems that are often needed (and available) at companies or in the open-source community (#1 above).

Refer to these slides [2] by Jeff Dean for DS design patterns and tradeoff analysis advice (#2 and #3 above). We'll only include here one example back-of-the-envelope calculation. Note the final quiz may

Numbers Everyone Should Know

(NB: Numbers are outdated, keep searching for latest numbers online, e.g., [4])

L1 cache reference	0.	.5 ns
Branch mispredict	5	ns
L2 cache reference	7	ns
Mutex lock/unlock	100	ns
Main memory reference	100	ns
Compress 1K bytes with Zippy	10,000	ns
Send 2K bytes over 1 Gbps network	20,000	ns
Read 1 MB sequentially from memory	250,000	ns
Round trip within same datacenter	500,000	ns
Disk seek	10,000,000	ns
Read 1 MB sequentially from network	10,000,000	ns
Read 1 MB sequentially from disk	30,000,000	ns
Send packet CA->Netherlands->CA	150,000,000	ns

Calculation 1: Thumbnail Page Generation



Question: How long to generate the image thumbnail page for an album of 30 pics (256KB/thumbnail)?

- Consider at least two designs for how the album app might interact with the file system to retrieve the thumbnails. Assume local application, no network/distribution.
- Use "Numbers Everyone Should Know" (previous slide) to give an order of magnitude estimation of the runtime under each design.
- In your answer sheet, briefly describe your options, give your assessment for runtime for each, and identify whether there is a clear winner?

https://tinyurl.com/back-of-the-envelope-activity

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Source: Jeff Dean, https://static.googleusercontent.com/media/research.google.com/en//people/jeff/stanford-295-talk.pdf

Calculation 1: Thumbnail Page Generation

Design 1: Read serially, thumbnail 256K images on the fly

30 seeks * 10 ms/seek + 30 * 256K / 30 MB/s = 560 ms

Design 2: Issue reads in parallel:

10 ms/seek + 256 K read / 30 MB/s = 18 ms

(Assumes full parallelism, so multiple disks each with multiple heads. If all in one disk with (say) 5 heads, latency is more like 110ms.)

Lots of variations:

- caching (single images? whole sets of thumbnails?)
- pre-computing thumbnails

- ...

Back of the envelope helps identify most promising...

Calculation 2: Quicksort 1GB Numbers

```
algorithm quicksort(A, lo, hi) is
  if lo < hi then
    p := partition(A, lo, hi)
    quicksort(A, lo, p - 1)
    quicksort(A, p + 1, hi)
algorithm partition(A, lo, hi) is
  pivot := A[hi]
  i := lo
  for j := lo to hi do
    if A[j] < pivot then
       swap A[i] with A[j]
       i := i + 1
  swap A[i] with A[hi]
  return i
```

```
quicksort(A, 0, length(A) - 1).
```

```
Mispredictions: 2^32 mispredivtios * 5ns = 21 seconds
Memory component: 28GB @ 4GB/s = 7 seconds
```

```
30 seconds for sorting a 1GB-worth of numbers
```

Question: How long to quicksort 1GB's worth of 4-byte numbers?

- Assume all numbers are in RAM.
- Think about how many numbers that would mean. → 2²28 numbers = n
- Remind yourselves of the algorithm and think of what the most expensive operations are likely to be. → 1) branch mispredictions (due to comparisons); 2) memory accesses
- For each expensive operation:
 - Approximate how many such ops on average.
 - 1) # comparisons: n log n = 2^28*28 ~= 2^33. Half mispredict: 2^32 branch mispredictions
 - 2) amount of memory accessed:
 28 * 1GB = 28 GB RAM accessed
 - Use "Numbers Everyone Should Know"

Calculation 2: Quicksort 1GB Numbers

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Question: How long to quicksort 1GB's worth of 4-byte numbers?

- Assume all numbers are in RAM.
- Think about how many numbers that would mean.
- Remind yourselves of the algorithm and think of what the most expensive operations are likely to be.
- For each expensive operation:
 - Approximate how many such ops on average.
 - Use "Numbers Everyone Should Know" to approximate the total cost of those ops.
- Then add things up and put your order of magnitude estimation in your answer sheet.

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```
Mispredictions = 2^32 misp * 5 ns
=~ 21 sec
```

```
Memory: 28 GB @ 4GB/s =~ 7 sec
```

Question: How long to quicksort 1 GB of 4 byte numbers?

- Assume all numbers are in RAM.
- Think about how many numbers that would mean. $\rightarrow 2^{28}$ numbers
- Remind yourselves of the algorithm and think of what the most expensive operations are likely to be. → comparisons, memory reads
 For each heavy operation:
 - Approximate how many such ops on average. → comparisons: log(2^28) passes over 2^28 numbers, or 2^33 comparisons. Half mispredict, so 2^32 mispredictions.

\rightarrow amount of memory read: 2^30 bytes for 28 passes.

- Use "Numbers Everyone Should Know" to approximate the total cost of those ops.
- Then add things up and put your order of magnitude estimation in your answer sheet.

Calculation 2: Quicksort 1GB Numbers

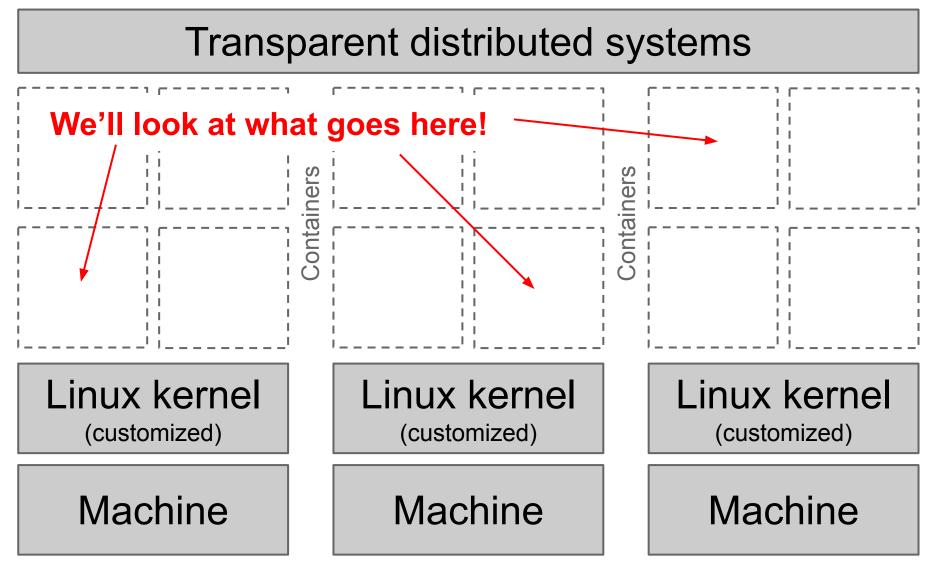
Comparisons: lots of unpredictable branches log(2^28) passes over 2^28 numbers = ~2^33 comparisons ~1/2 will mispredict, so 2^32 mispredicts * 5 ns/mispredict = 21 secs

Memory bandwidth: mostly sequential streaming 2^30 bytes * 28 passes = 28 GB. Memory BW is ~4 GB/s, so ~7 secs

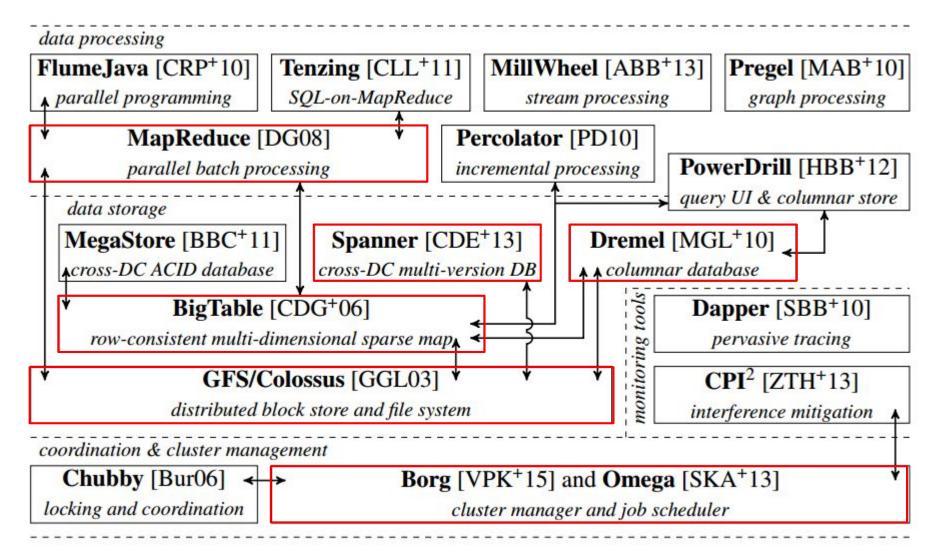
So, it should take ~30 seconds to sort 1 GB on one CPU

Source: Jeff Dean, https://static.googleusercontent.com/media/research.google.com/en//people/jeff/Stanford-DL-Nov-2010.pdf

Software Systems Stack



The **Google** Stack



Example Infrastructure System: Kubernetes Cluster Orchestrator

Kubernetes (K8s)

https://kubernetes.io/

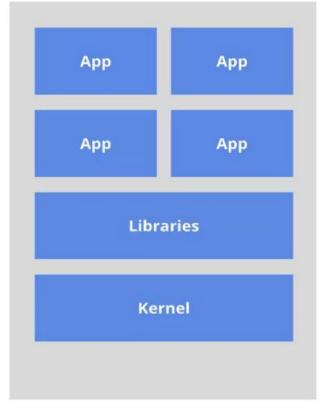
- Open-source system for automating deployment, scaling, and management of containerized applications.
- Groups containers that make up an application into logical units for easy management, scaling, and discovery.
- Builds upon 15 years of experience of running production workloads at Google, combined with best-of-breed ideas and practices from the community.



Background: Containers

Virtual Machines

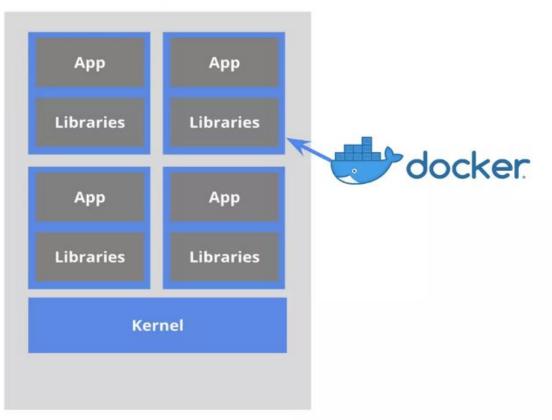
The old way: Applications on host



Heavyweight, non-portable Relies on OS package manager

Containers

The new way: Deploy containers

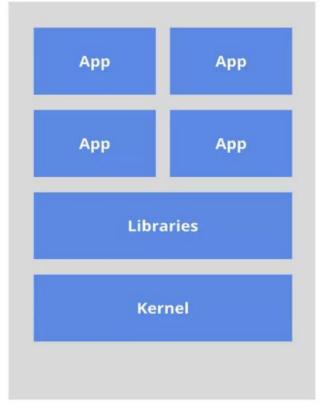


Small and fast, portable Uses OS-level virtualization

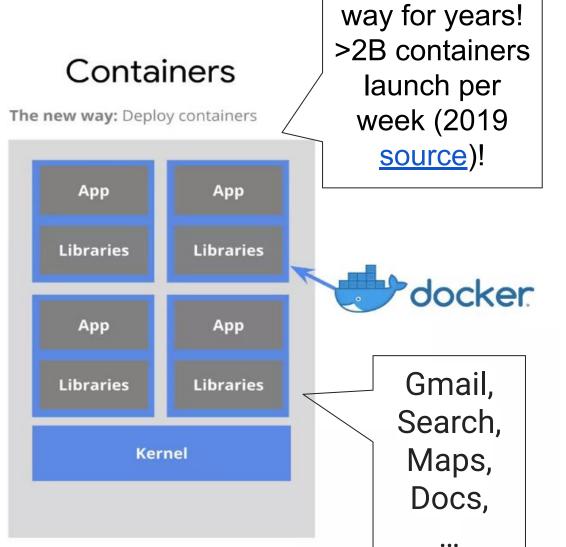
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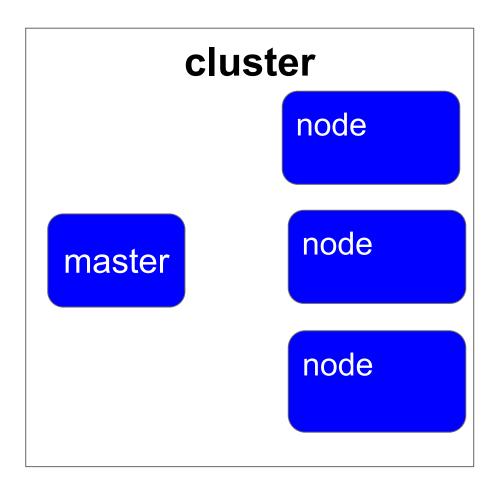


Small and fast, portable Uses OS-level virtualization

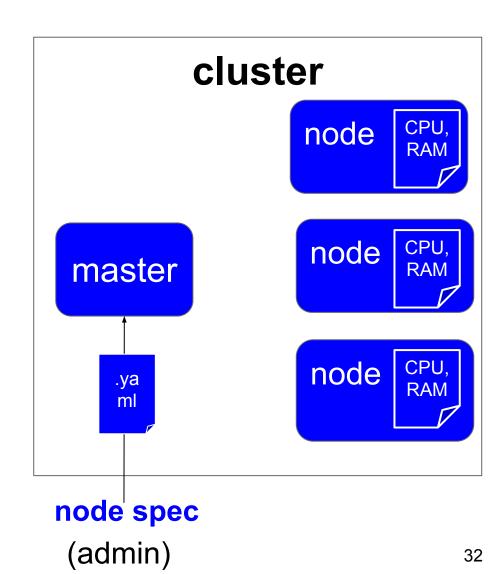
Google's been

running this

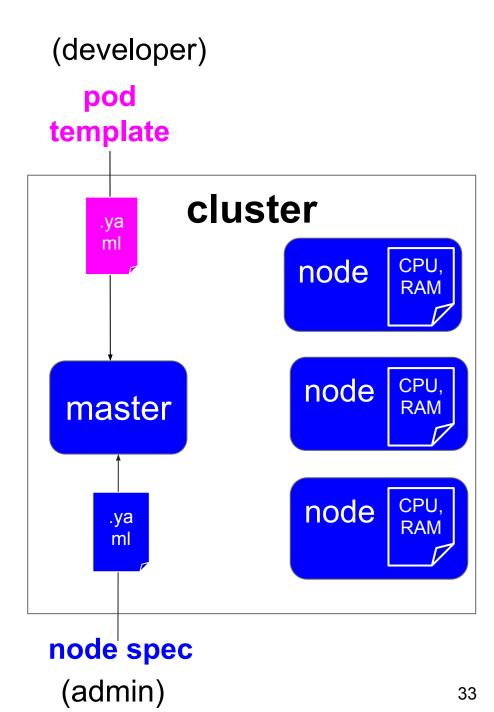
• K8s runs applications in a **cluster** of **nodes**.



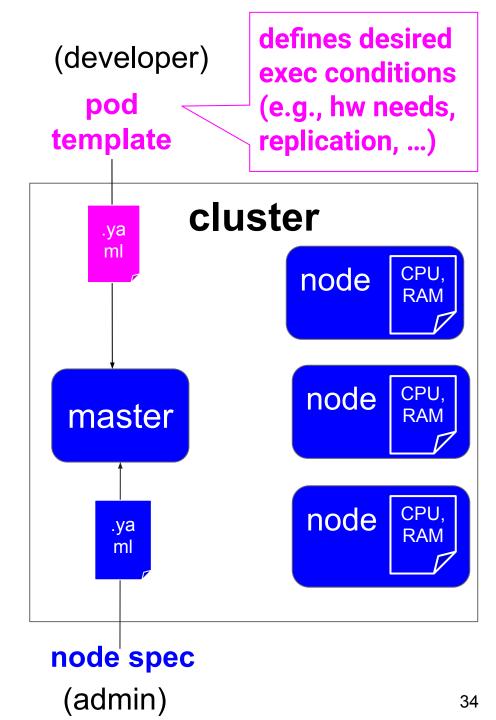
- K8s runs applications in a cluster of nodes.
- Nodes abstract out computing resources: can be physical machines or VMs; they are registered with specified amts of CPU, RAM, GPU, ...



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- Nodes abstract out computing resources: can be physical machines or VMs; they are registered with specified amts of CPU, RAM, GPU, ...
- Applications are called pods and consist of one or more containers, which the developer specifies in a .yaml file to k8s master.

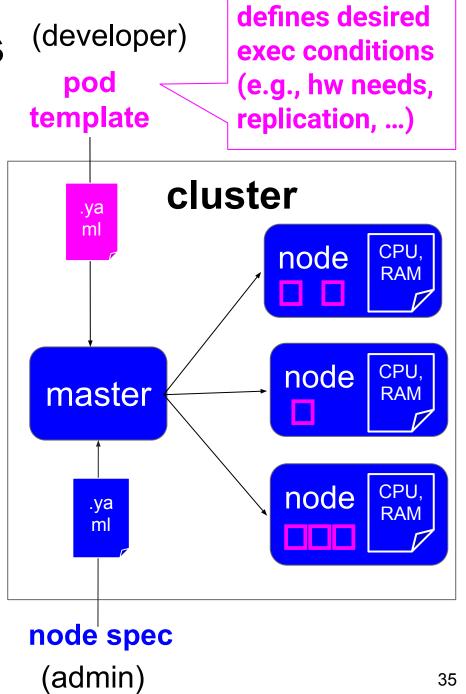


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K8s main functions

- Based on pod templates, selects suitable nodes and instantiates pods on them for execution.
- Continuously does that to ensure that, despite failures, the desired execution conditions for all pods are met.



Many more K8s functions

(from https://kubernetes.io/)

- Automated rollouts and rollbacks
- Service discovery and load balancing
- Storage orchestration
- Self-healing
- Automatic scheduling (bin packing)
- Secret and configuration management
- Batch execution
- Horizontal auto-scaling
- Designed for extensibility

Many more K8s functions

(from https://kubernetes.io/)

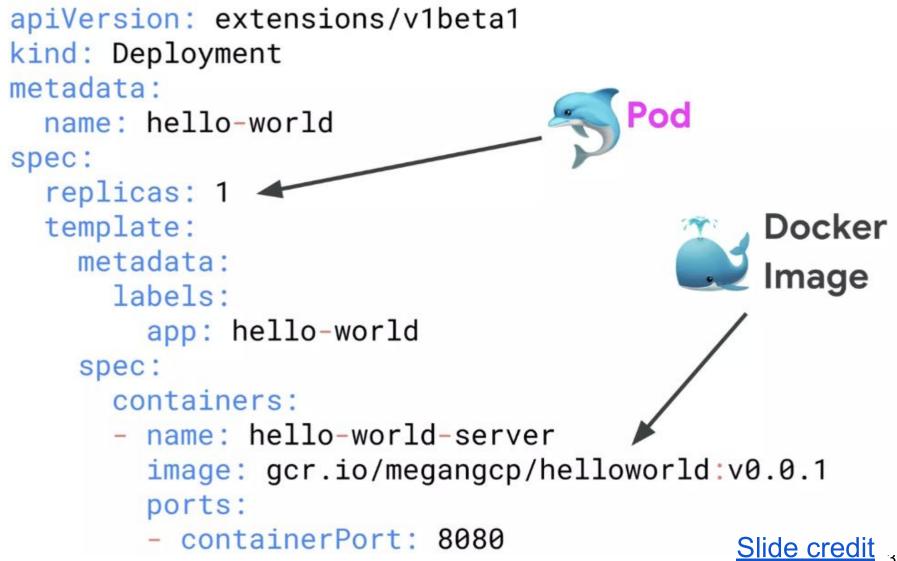
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EVEN MORE functions have been built outside of K8s, through its extension by third parties, demonstrating the value of extensible design for infra systems!

K8s outline

- Examples
 - Hello World
 - o <u>Busybox</u>
 - o <u>Nginx</u>
- System architecture (how it works)
- Extensibility
 - Argo workflows
 - Kubeflow pipelines
 - Ray on Kubernetes

Example: Hello World



```
apiVersion: v1
kind: Service
metadata:
  name: helloworld
spec:
  selector:
    app: hello-world
  ports:
  - name: http
    protocol: TCP
                                  Allow
                                 traffic in
    port: 80
    targetPort: 8080
  type: LoadBalancer
```

kubectl apply -f deployment.yaml

deployment.extensions/hello-world created



After a while...

kubectl get pods

NAME READY STATUS RESTARTS hello-world-84c646556b-kn59b 1/1 Running 0

kubectl get svc

NAMETYPECLUSTER-IPEXTERNAL-IPhelloworldLoadBalancer10.51.246.335.188.110.209

Slide credit 42

After a while...

curl <u>http://35.188.110.209</u>

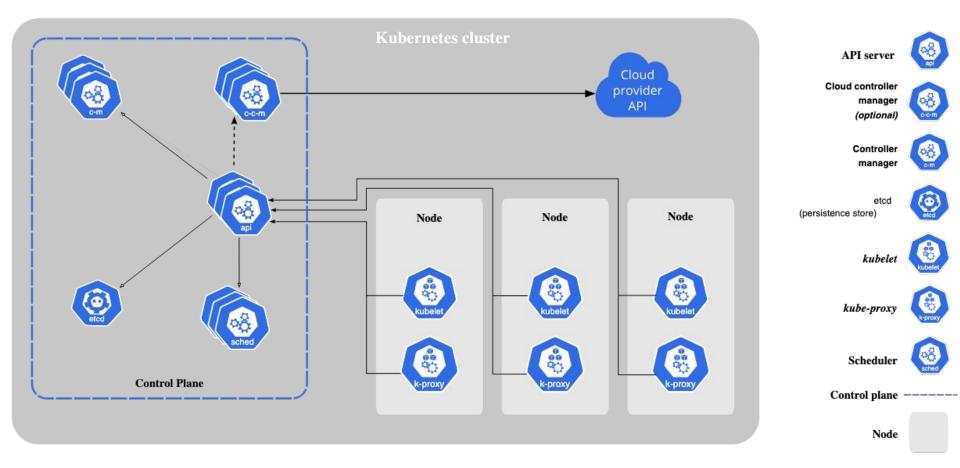
Hello world!



K8s outline

- Examples
 - Hello World
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- System architecture (how it works)
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System architecture



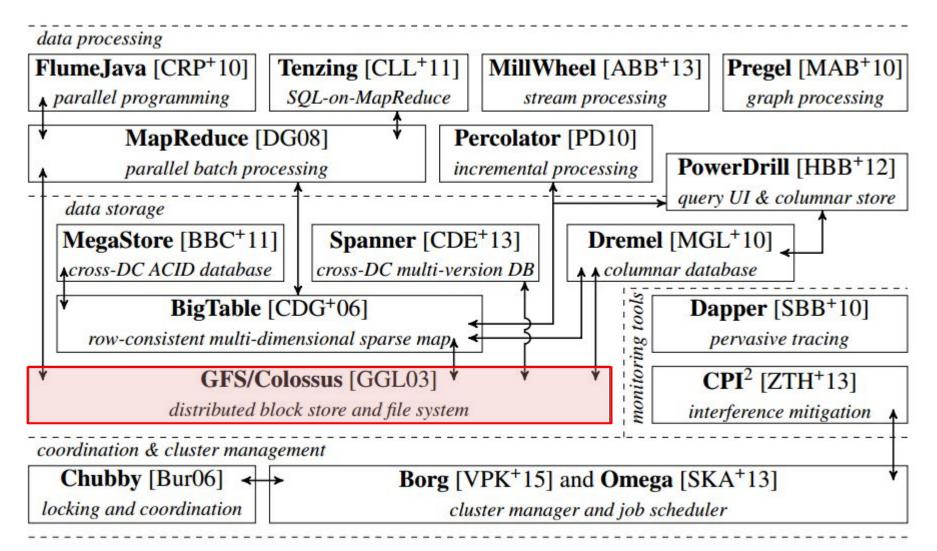
Functionality detailed in: <u>docs</u>. RG describes the core aspects of the design.

K8s outline

- Examples
 - Hello World
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 - <u>Nginx</u> (from doc)
- System architecture (how it works)
- Extensibility (from docs)
 - Argo workflows: <u>overview</u>, <u>steps example</u>, a<u>rtifact</u> <u>passing example</u>, <u>dag example</u>
 - Kubeflow pipelines: <u>example</u>
 - Ray on Kubernetes: <u>docs</u>

THE FOLLOWING SLIDES IN THIS PRESENTATION ARE NOT SUBJECT FOR THE EXAM.

The **Google** Stack



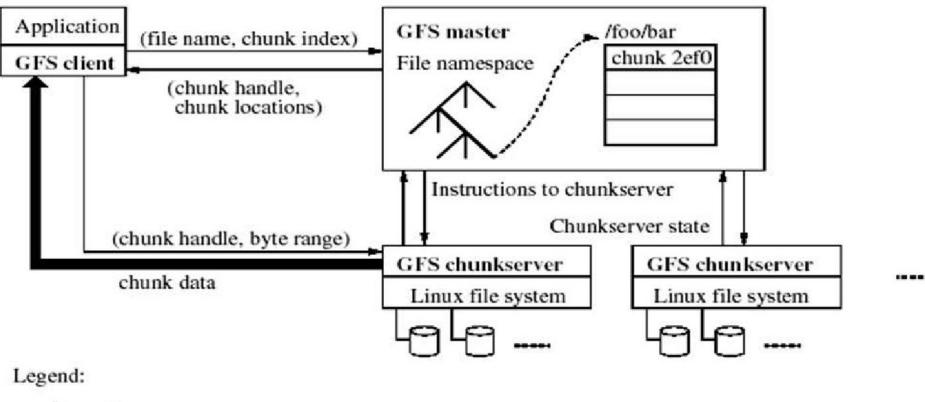
GFS/Colossus

- Bulk data block storage system
 - Optimized for large files (GB-size)
 - Supports small files, but not common case
 - Read, write, record-append modes
 - Record appends are the only one that gives clean semantics: atomic append at least once.

• **Colossus** = GFSv2, adds some improvements

- e.g., Reed-Solomon-based erasure coding
- better support for latency-sensitive applications
- **sharded meta-data** layer, rather than single master

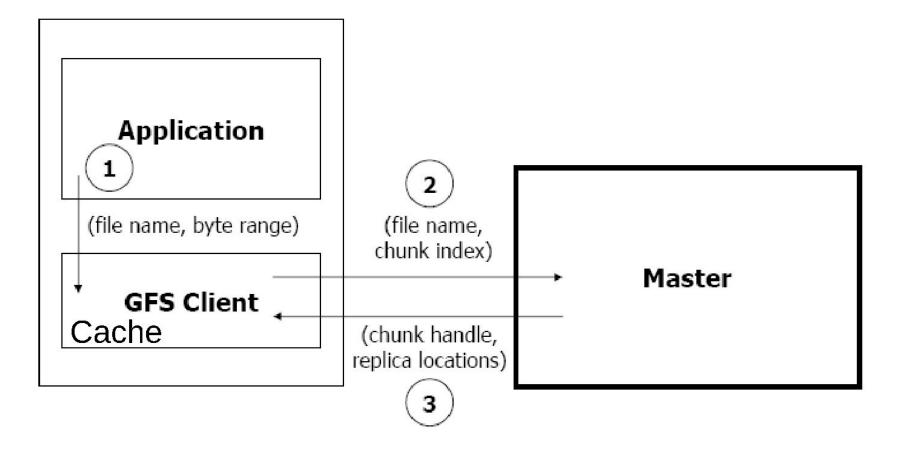
GFS/Colossus: architecture



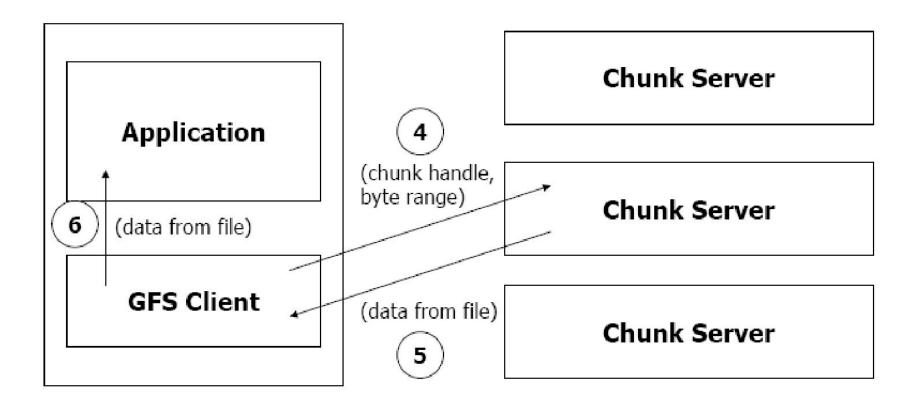
⇒

Data messages Control messages

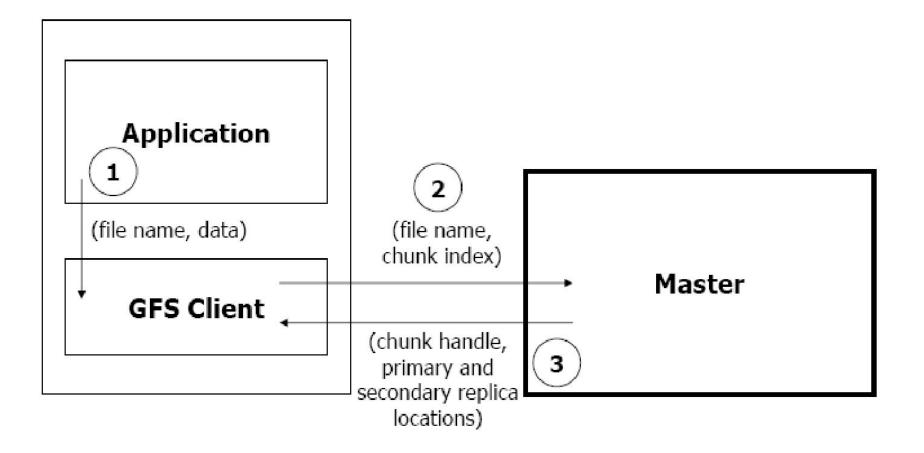
Read Protocol



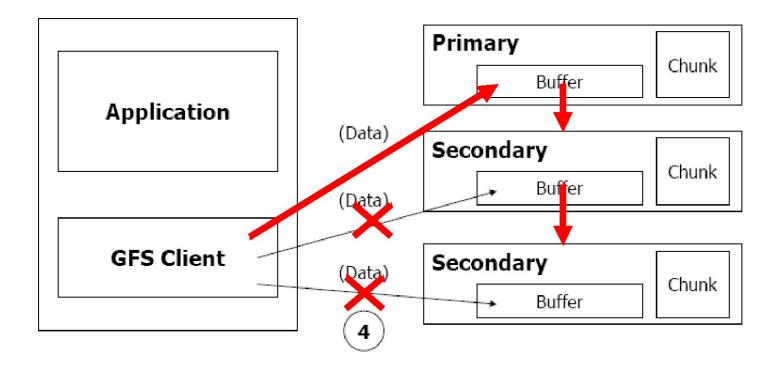
Read Protocol



Write Protocol



Write Protocol



Primary enforces one order across all writes to a file. Thus, block writes are consistent but undefined in GFS.

Record Append Protocol

- The client specifies only the data, not the file offset
 - File offset is chosen by the primary
 - Why do they have this?

Record Append Protocol

- The client specifies only the data, not the file offset
 - File offset is chosen by the primary
 - Why do they have this?
- To provide meaningful semantic: at least once atomically
 - Because FS is not constrained Re: where to place data, it can get atomicity without sacrificing concurrency
- Rough mechanism:
 - If record fits in chunk, primary chooses the offset and communicates it to all replicas
 [] offset is arbitrary
 - If record doesn't fit in chunk, the chunk is padded and client gets failure
 [ile may have blank spaces
 - If a record append fails at any replica, the client retries the

Detailed algo

Application originates record append request.

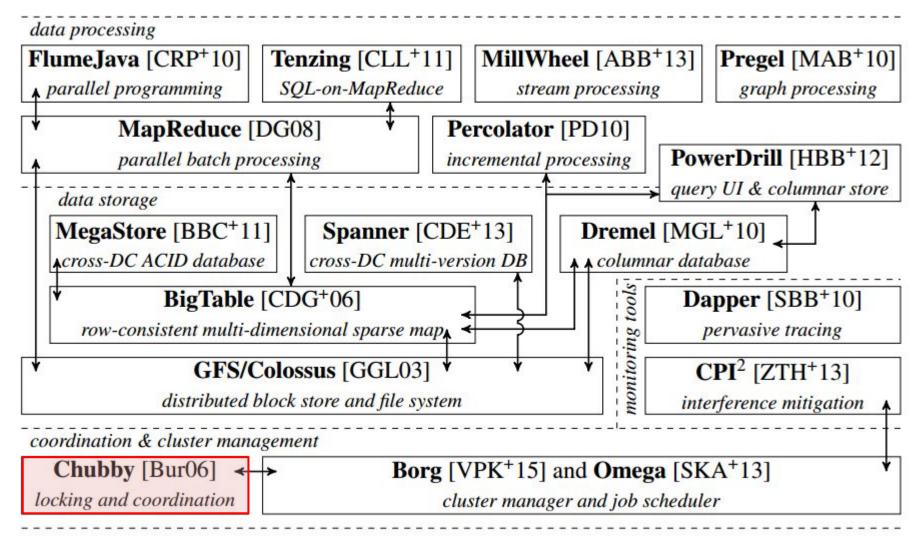
- 2. GFS client translates request and sends it to master.
- 3. Master responds with chunk handle and (primary + secondary) replica locations.
- 4. Client pushes write data to all locations.
- 5. Primary checks if record fits in specified chunk.
- 6. If record does not fit, then:
 - The primary pads the chunk, tells secondaries to do the same, and informs the client.
 - Client then retries the append with the next chunk.
- 7. If record fits, then the primary:
 - appends the record at some offset in chunk,
 - tells secondaries to do the same (specifies offset),
 - receives responses from secondaries,

Implications of weak semantics

- Relying on appends rather on overwrites
- Writing self-validating records

 Checksums to detect and remove padding
- Self-identifying records
 - Unique Identifiers to identify and discard *duplicates*
- Hence, applications need to adapt to GFS and be aware of its inconsistent semantics
- BUT: You can implement a (transaction) log replication protocol on it, so it's a useful building block toward a stronger-semantic system.

The **Google** Stack



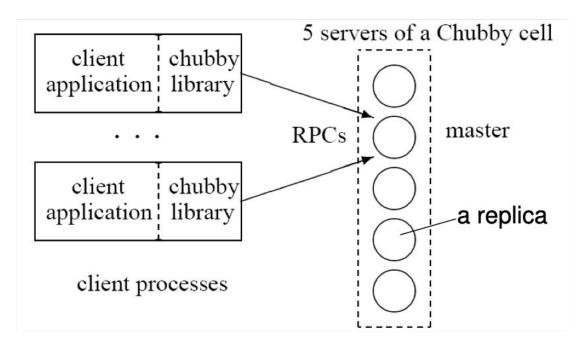
Details & Bibliography: http://malteschwarzkopf.de/research/assets/google-stack.pdf

Figure from M. Schwarzkopf, "Operating system support for warehouse-scale computing", PhD thesis, University of Cambridge, 2015.

Chubby (2004)

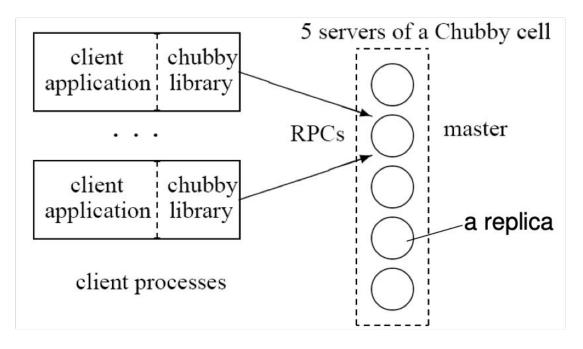
- Lock Service
- UNIX-like file system interface
- Reliability and availability
- Chubby uses Paxos for everything
 - Propagate writes to a file
 - Choosing a Master
 - Even for adding new Chubby servers to a Chubby cell
 - Used by many services at Google (Colossus, Bigtable)
 - Open-source version is called Zookeeper, also used as building block in many systems

System Architecture



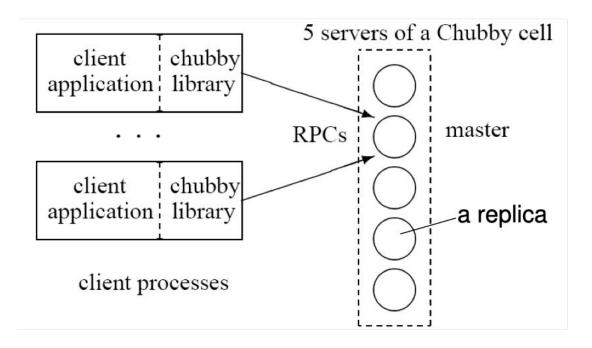
- A chubby cell consists of a small set of servers (replicas)
 - Placed in different racks, so as to minimize chance of correlated failures
- A master is elected from the replicas via Paxos
 - Master lease: several seconds
 - If master fails, a new one will be elected, but only after master leases expire
- Client talks to the master via the chubby library
 - All replicas are listed in DNS; clients discover master by talking to any replica

System Architecture (2)



- Replicas maintain copies of a simple database
- Clients send read/write requests only to the master
- For a write:
 - The master propagates it to replicas via Paxos
 - Replies after the write reaches a majority of replicas
- For a read:
 - The master satisfies the read alone

System Architecture (3)



- If a replica fails and does not recover for a long time (a few hours)
 - A fresh machine is selected to be a new replica, replacing the failed one
 - It updates the DNS
 - Obtains a recent copy of the database
 - The current master polls DNS periodically to discover new replicas
 - Integrating the new replica into the group is another Paxos run

Interface

- Supports a hierarchical namespace for lock files.
 - /ls/foo/OurPrimaryServer.lck
 - First component (Is): lock service (common to all names)
 - Second component (foo): the chubby cell (used in DNS lookup to find the Chubby master)
 - The rest: lock file name inside the cell

Supports:

- Atomic create, delete, atomic read of full contents, atomic write of full contents, etc.
- Reader and writer locks
- Clients can subscribe to events (modifications of Chubby

APIs

- Open()
 - Mode: read/write/change ACL; Events; Lock-delay
 - Create new file or directory?
- Close()
- GetContentsAndStat(), GetStat(), ReadDir()
- SetContents(): set all contents; SetACL()
- Delete()
- Locks: Acquire(), TryAcquire(), Release()
- Sequencers: GetSequencer(), SetSequencer(), CheckSequencer()

Example: Primary Election

Open("/ls/foo/OurServicePrimary", "write mode"); if (successful) {

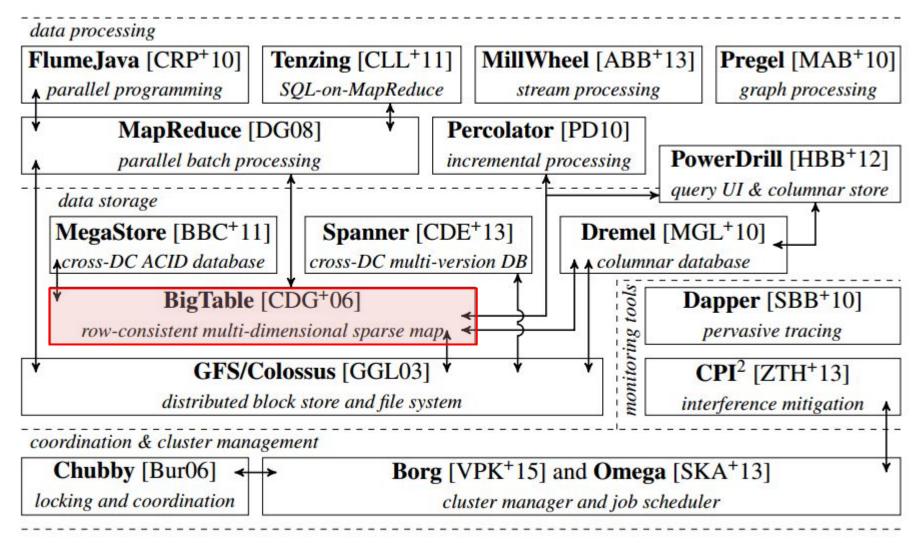
// primary

SetContents(primary_identity);

} else {

// replica

The **Google** Stack



Details & Bibliography: http://malteschwarzkopf.de/research/assets/google-stack.pdf

Figure from M. Schwarzkopf, "Operating system support for warehouse-scale computing", PhD thesis, University of Cambridge, 2015.

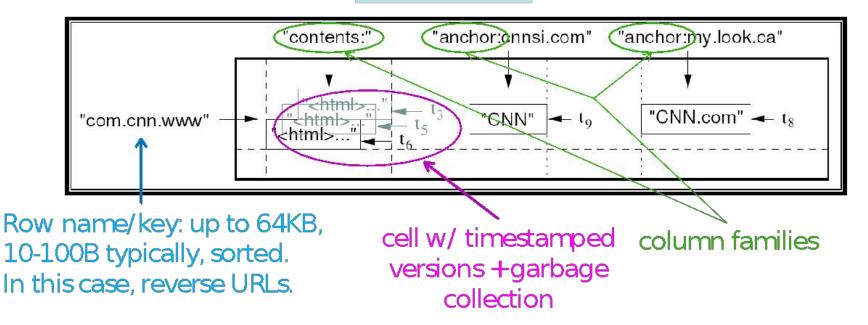
BigTable (2006)

• "A Bigtable is a sparse, distributed, persistent multidimensional sorted map"

(row:string, column:string, timestamp:int64) \rightarrow string

• Example: the (simplified) schema of the Webtable:

Webtable

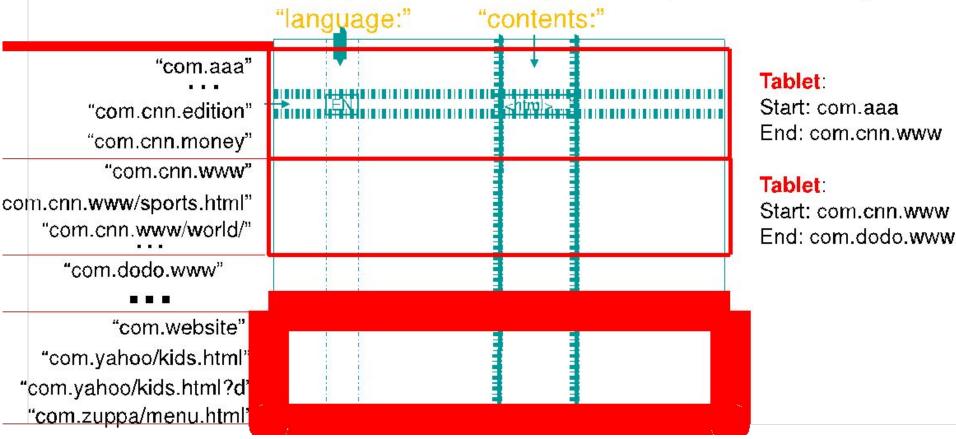


Key Ideas

- Distributed tablets hold shards of the map
- Reads & writes within a row are transactional
 - Independently of the number of columns touched
 - But: no cross-row transactions possible
 - Turns out users find this hard to deal with
- Example of good principles for DS design:
 - **stateless design** (stores all state in Colossus, Chubby)
 - layered design (relies on other services and structures)
 - recursive design (tablet server locations are stored in Biotable itself)

Tablets

- A Bigtable table is partitioned into many tablets based on row keys
 - Tablets (100-200MB each) are stored in a particular structure in GFS
- Each tablet is served by one tablet server
 - Tablets are stateless (all state is in GFS), hence they can restart at any time



The Bigtable API

- Metadata operations
 - Create/delete tables, column families, change metadata
- Writes: Single-row, atomic
 - Set(): write cells in a row
 - DeleteCells(): delete cells in a row
 - DeleteRow(): delete all cells in a row
- Reads: Scanner abstraction
 - Allows to read arbitrary cells in a Bigtable table
 - Each row read is atomic
 - · Can restrict returned rows to a particular range
 - Can ask for just data from 1 row (getter), all rows (scanner), etc.
 - Can ask for all columns, just certain column families, or specific columns
 - · Can ask for certain timestamps only

API Examples: Write



atomic row modification

No support for (RDBMS-style) multi-row transactions

Servers

- Library linked into every client
- One master server
 - Assigns/load-balances tablets to tablet servers
 - Detects up/down tablet servers
 - Garbage collects deleted tablets
 - Coordinates metadata updates (e.g., create table, ...)
 - Does **NOT** provide tablet location (we'll see how this is gotten)
 - Master is stateless state is in Chubby and... Bigtable (recursively)!
- Many tablet servers
 - Tablet servers handle R/W requests to their tablets
 - Split tablets that have grown too large
 - Tablet servers are also stateless their state is in GFS!

Chubby & Colossus State

Chubby state:

/ls/bt/master-server /ls/bt/live-tablet-servers/ /ID1 /ID2

/ls/bt/first-metadata-server

Colossus state: /fs/bt/tabletID1/ /log **/SS1 /**SS2 /fs/bt/tabletID2/ . . .

Tablet Assignment

- 1 Tablet => 1 Tablet server
- Master
 - keeps tracks of set of live tablet serves and unassigned tablets
 - Master sends a tablet load request for unassigned tablet to the tablet server
- Bigtable uses Chubby to keep track of tablet servers
- On startup a tablet server:
 - Tablet server creates and acquires an exclusive lock on uniquely named file in Chubby directory
 - Master monitors the above directory to discover tablet servers
- · Tablet server stops serving tablets if it loses its exclusive lock
 - Tries to reacquire the lock on its file as long as the file still exists

Tablet Assignment

- If the file no longer exists, tablet server not able to serve again and kills itself
- Master is responsible for finding when tablet server is no longer serving its tablets and reassigning those tablets as soon as possible.
- Master detects by checking periodically the status of the lock of each tablet server.
 - If tablet server reports the loss of lock
 - Or if master could not reach tablet server after several attempts.

Tablet Assignment

- Master tries to acquire an exclusive lock on server's file.
 - If master is able to acquire lock, then chubby is alive and tablet server is either dead or having trouble reaching chubby.
 - If so master makes sure that tablet server never can server again by deleting its server file.
 - Master moves all tablets assigned to that server into set of unassigned tablets.
- If Chubby session expires, master kills itself.
- When master is started, it needs to discover the current tablet assignment.

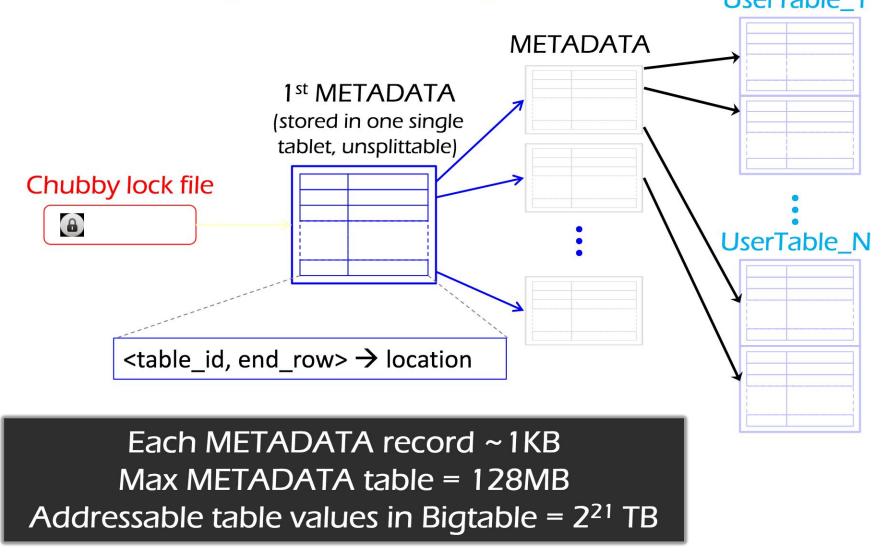
Master Startup Operation

- Grabs unique master lock in Chubby
 - Prevents server instantiations
- Scans directory in Chubby for live servers
- Communicates with every live tablet server
 - Discover all tablets
- Scans METADATA table to learn the set of tablets
 - Unassigned tables are marked for assignment

Locating Tablets

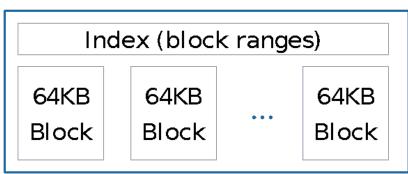
- Since tablets move around from server to server, given a row, how do clients find the right machine?
 - Tablet properties: startRowIndex and endRowIndex
 - Need to find tablet whose row range covers the target row
- One approach: could use the Bigtable master
 - Central server almost certainly would be bottleneck in large system
- Instead: store special tables containing tablet location info in the Bigtable cell itself (recursive design ③)

Tablets are located using a hierarchical structure (B+ tree-like)



Tablet storage and R/W operation

- Uses Google SSTables, a key building block
- Without going into much detail, an SSTable:
 - Is an immutable, sorted file of key-value pairs
 - SSTable files are stored in GFS
 - Keys are: <row, column, timestamp>
 - SSTables allow only appends, no updates (delete possible)
 - Why do you think they don't use something that supports updates?



SSTable

Read/Write Operations

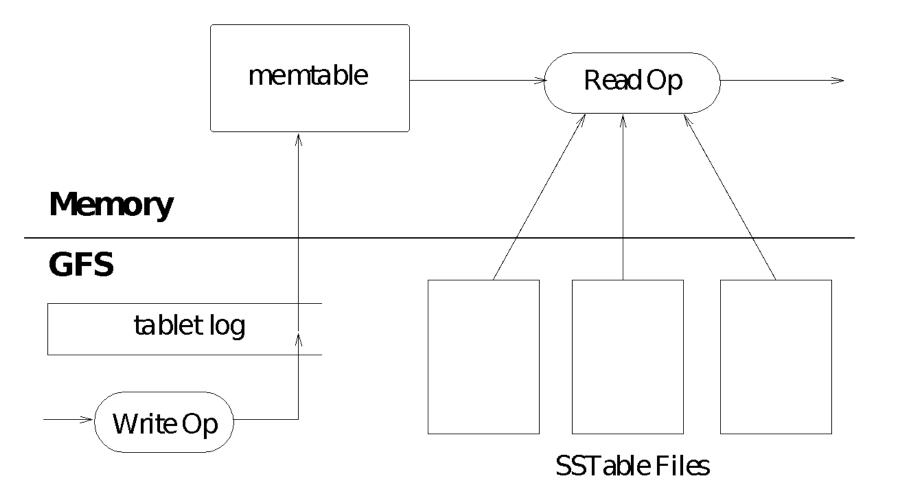
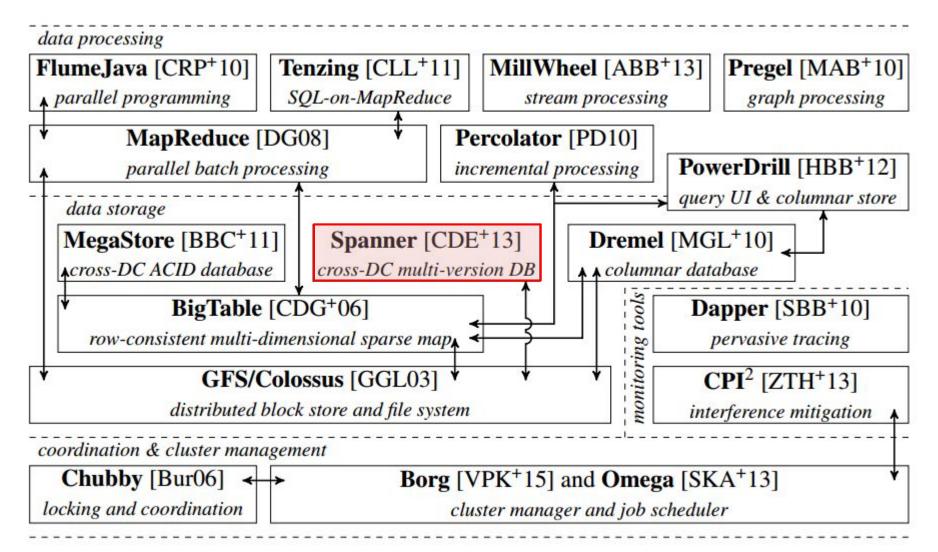


Figure 5: Tablet Representation

The **Google** Stack

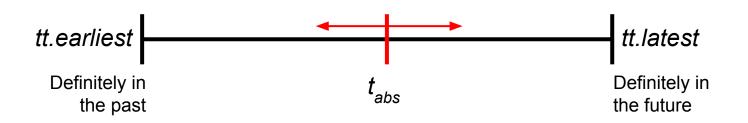


Spanner (2012)

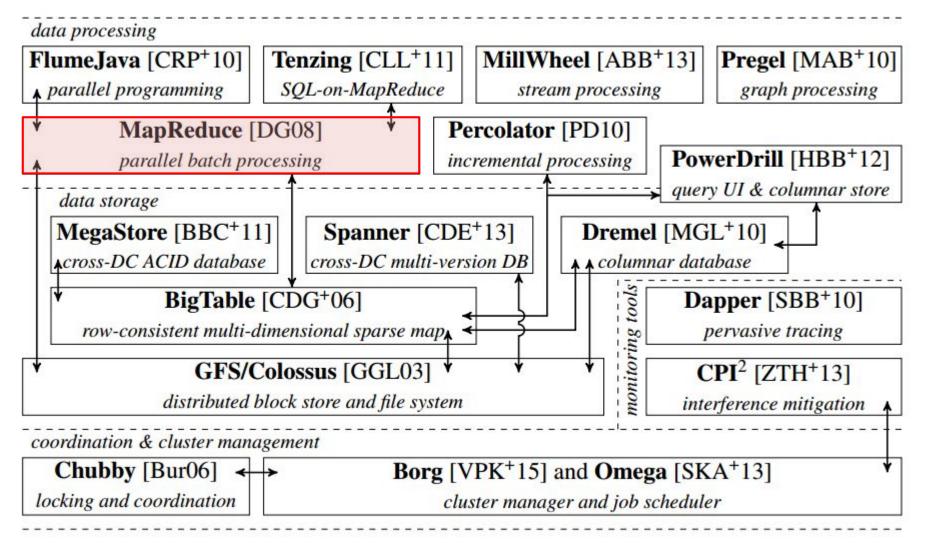
- BigTable insufficient for some consistency needs
- Often have transactions across >1 data centres
 - May buy app on Play Store while travelling in the U.S.
 - Hit U.S. server, but customer billing data is in U.K.
 - Or may need to update several replicas for fault tolerance
- Wide-area consistency is hard
 - due to long delays and clock skew
 - no global, universal notion of time
 - NTP not accurate enough, PTP doesn't work (jittery links)

Spanner (2012)

- Spanner offers transactional consistency: full RDBMS power, ACID properties, at global scale!
- Secret sauce: hardware-assisted clock sync
 Using GPS and atomic clocks in data centres
- Use global timestamps and Paxos to reach consensus
 - Still have a period of uncertainty for write TX: wait it out!
 - Each timestamp is an **interval**:



The **Google** Stack

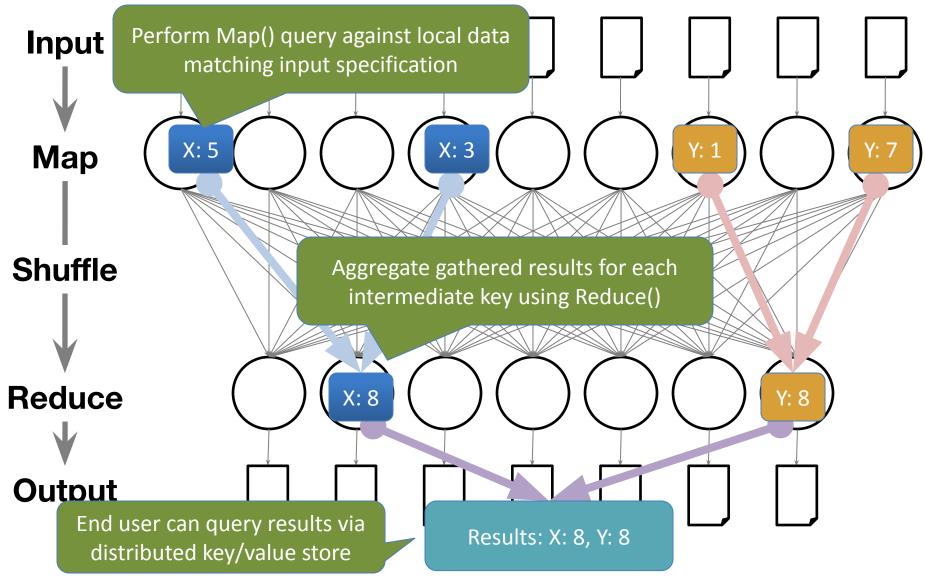


Details & Bibliography: http://malteschwarzkopf.de/research/assets/google-stack.pdf

MapReduce (2004)

- Parallel programming framework for scale
 - Run a program on 100's to 10,000's machines
- Framework takes care of:
 - Parallelization, distribution, load-balancing, scaling up (or down) & fault-tolerance
- Accessible: programmer provides two methods ;-)
 - map(key, value) \rightarrow list of <key', value'> pairs
 - reduce(key', value') \rightarrow result
 - Inspired by functional programming

MapReduce

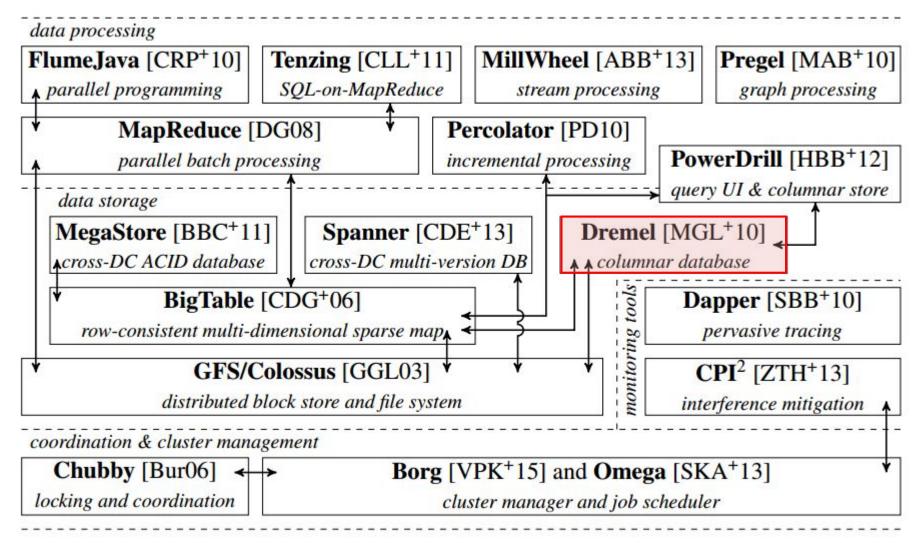


Slide originally due to S. Hand's distributed systems lecture course at Cambridge: http://www.cl.cam.ac.uk/teaching/1112/ConcDisSys/DistributedSystems-1B-H4.pdf

MapReduce: Pros & Cons

- Extremely simple, and:
 - Can auto-parallelize (since operations on every element in input are independent)
 - Can auto-distribute (since rely on underlying Colossus/BigTable distributed storage)
 - Gets fault-tolerance (since tasks are idempotent, i.e. can just re-execute if a machine crashes)
- Doesn't really use **any** sophisticated distributed systems algorithms (except storage replication)
- However, not a panacea:
 - Limited to batch jobs, and computations which are expressible as a map() followed by a reduce()

The **Google** Stack

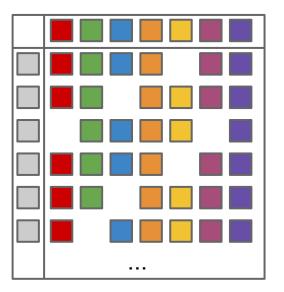


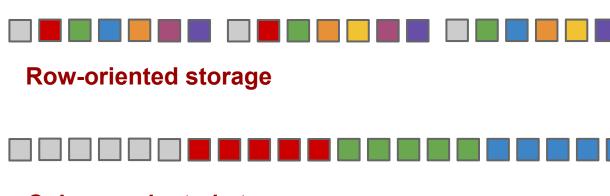
Details & Bibliography: http://malteschwarzkopf.de/research/assets/google-stack.pdf

Dremel (2010)

Column-oriented store

 $\circ~$ For quick, interactive queries





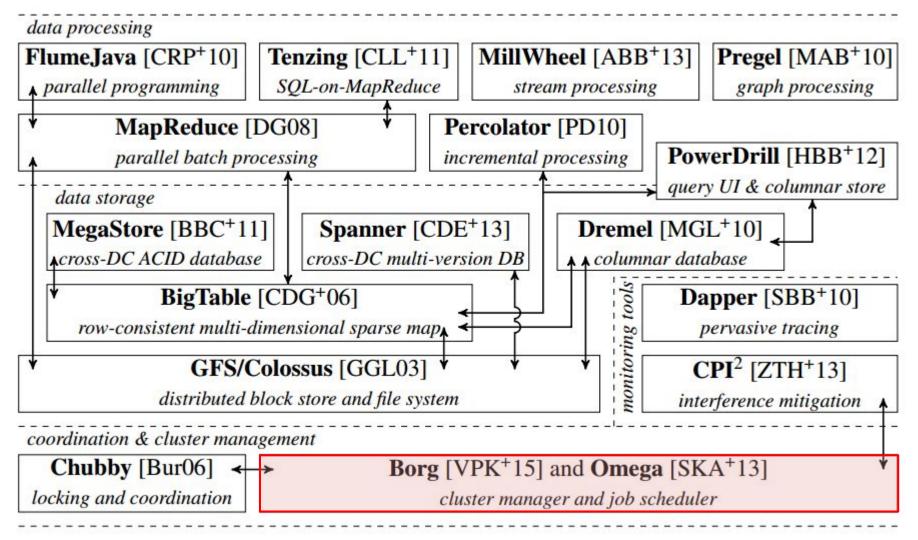
Column-oriented storage

Dremel (2010)

• Stores protocol buffers

- Google's universal serialization format
- \circ Nested messages \rightarrow nested columns
- \circ Repeated fields \rightarrow repeated records
- Efficient encoding
 - Many **sparse records**: don't store NULL fields
- Record re-assembly
 - Need to put results back together into records
 - Use a Finite State Machine (FSM) defined by protocol buffer structure

The **Google** Stack



Details & Bibliography: http://malteschwarzkopf.de/research/assets/google-stack.pdf

Borg

• Cluster manager and scheduler

- Tracks machine and task liveness
- Decides where to run what
- Consolidates workloads onto machines
 - Efficiency gain, cost savings
 - Need fewer clusters
- Watch Borg EuroSys'14 talk by John Wilkes: <u>https://www.youtube.com/watch?v=7MwxA4Fj2I</u> <u>4</u>

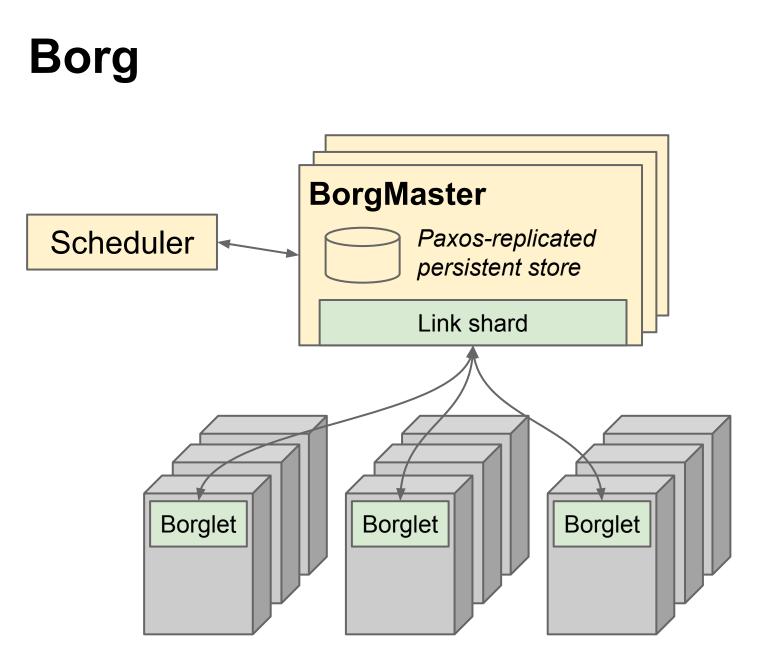


Figure reproduced after A. Verma et al., "Large-scale cluster management at Google with Borg", Proceedings of EuroSys 2015.

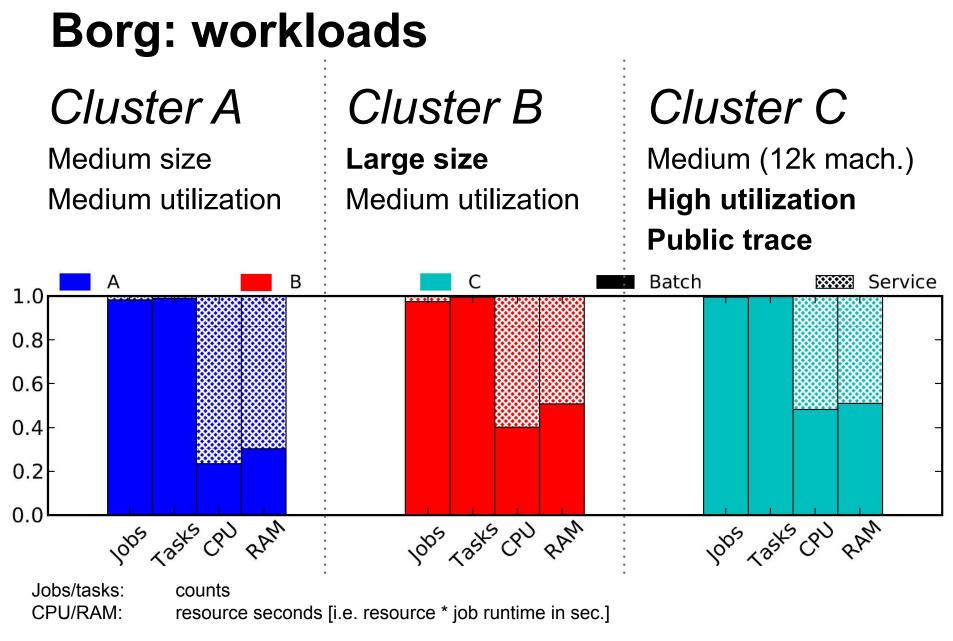


Figure from M. Schwarzkopf et al., "Omega: flexible, scalable schedulers for large compute clusters", Proceedings of EuroSys 2013.

Borg: workloads

Service jobs run for much longer than batch jobs: long-term user-facing services vs. one-off analytics.

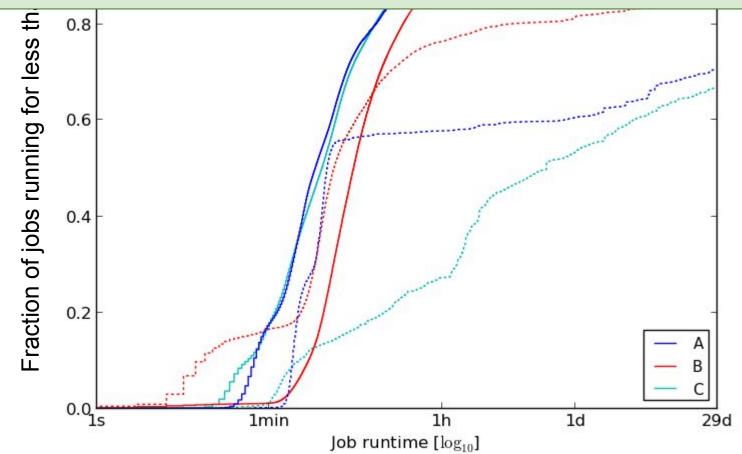


Figure from M. Schwarzkopf et al., "Omega: flexible, scalable schedulers for large compute clusters", Proceedings of EuroSys 2013.

Borg: workloads

Batch jobs arrive more frequently than service jobs: more numerous, shorter duration, fail more.

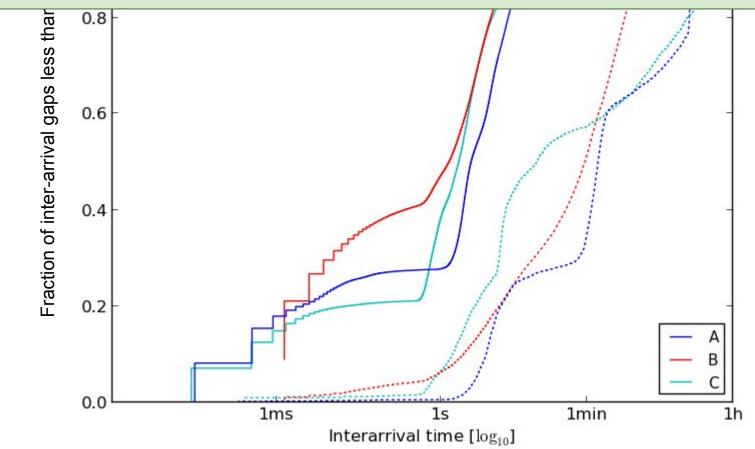
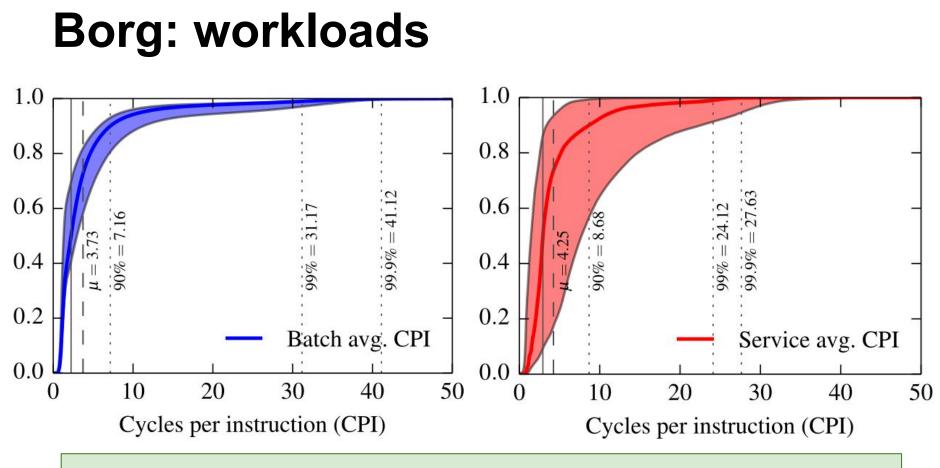
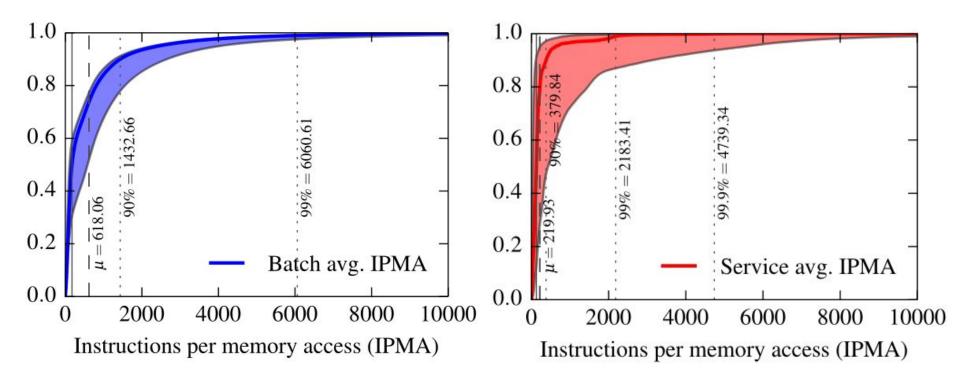


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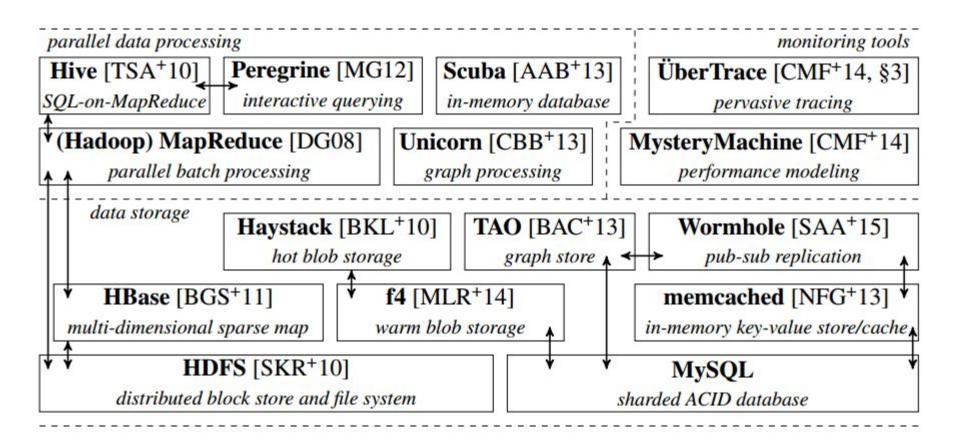
Batch jobs have a longer-tailed CPI distribution: lower scheduling priority in kernel scheduler.

Borg: workloads



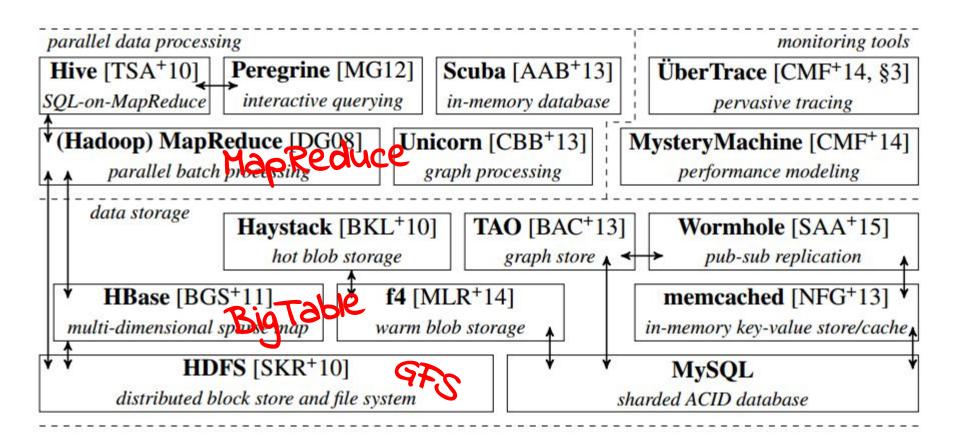
Service workloads access memory more frequently: larger working sets, less I/O.

The facebook Stack



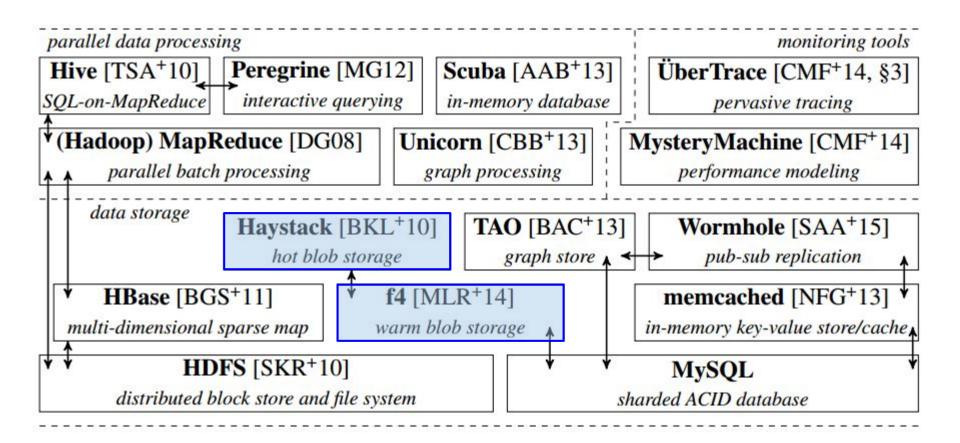
Details & Bibliography: http://malteschwarzkopf.de/research/assets/facebook-stack.pdf

The facebook Stack



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The facebook Stack



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Haystack & f4

- Blob stores, hold photos, videos
 - **not:** status updates, messages, like counts
- Items have a level of hotness
 - How many users are currently accessing this?
 - Baseline "cold" storage: MySQL
- Want to cache close to users
 - Reduces network traffic
 - Reduces latency
 - But cache capacity is limited!
 - Replicate for performance, not resilience

What about other companies' stacks?

How about other companies?

- Very similar stacks.
 - Microsoft, Yahoo, Twitter all similar in principle.

• Typical set-up:

- Front-end serving systems and fast back-ends.
- Batch data processing systems.
- Multi-tier structured/unstructured storage hierarchy.
- Coordination system and cluster scheduler.
- Minor differences owed to business focus
 - e.g., Amazon focused on inventory/shopping cart.

Open source software

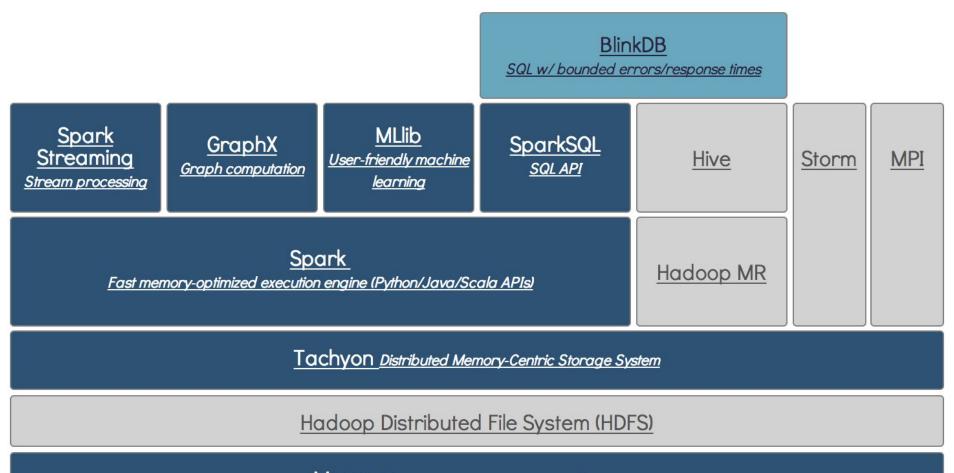
Lots of open-source implementations!

- MapReduce → <u>Hadoop</u>, <u>Spark</u>, <u>Metis</u>
- GFS \rightarrow HDFS
- BigTable → <u>HBase</u>, <u>Cassandra</u>
- Borg → <u>Mesos</u>, <u>Firmament</u>
- Chubby \rightarrow <u>Zookeeper</u>

But also some releases from companies...

- <u>Presto</u> (Facebook)
- <u>Kubernetes</u> (Google Borg)

The Spark Stack



Mesos Cluster resource manager, multi-tenancy





Newer Stacks

- Lots of new support for machine learning
 - Google: Tensorflow, Tensorflow Serving, Tensorflow Extended (TFX)
 - Uber: Michelangelo
 - Spark/Berkeley Data Stack (BDAS): MLBase, MLlib, Clipper

References

[1] Malte Schwartzkopf. "What does it taketo make Googlework at scale?" 2015. https://docs.google.com/presentation/d/10vJStE8aohGeI3y5BcY X8bBHwoHYCPu99A3KTTZEIr0/edit#slide=id.p.

[2] Jeff Dean. "Software Engineering Advice from Building Large–Scale Distributed Systems," 2007. https://static.googleusercontent.com/media/research.google.co m/en//people/jeff/stanford–295–talk.pdf.

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