Distributed Systems 1

CUCS Course 4113 https://systems.cs.columbia.edu/ds1-class/

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Atomic Commitment Protocols (Two-Phase Commit)

Context

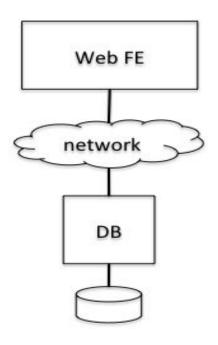
- We return to the distributed setting and discuss how **distributed transactions** are implemented.
- Why do we distribute and what are the main mechanisms?
 - Scalability: sharding
 - Fault tolerance: replication
- These mechanisms raise semantic challenges, which are addressed with rigorous protocols, such as:
 - Two-phase commit: atomic commitment protocol for sharding.
 - Paxos: a consensus protocol for replication.

Outline

- Motivating example
- Two-phase commit (2PC)
- 2PC limitations
- Next time: Paxos

Motivating Example

Example: Web Service Architecture

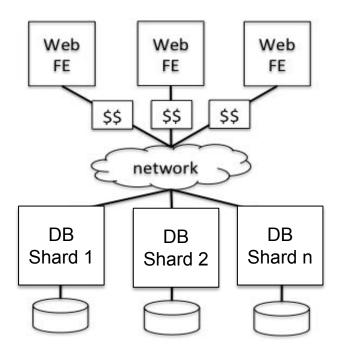


- Web front end (FE), database server (DB), network. FE is stateless, all state in DB.
- Suppose the FE implements a banking application (supporting account transfers, listings, and other functionality).
- Suppose the DB supports ACID transactions and the FE uses transactions.

Question: How do we make this:

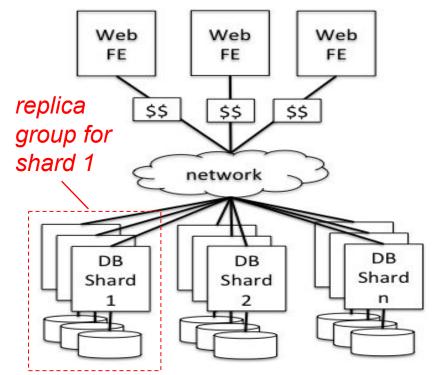
- scalable?
- fault tolerant?

Scalability: Sharding



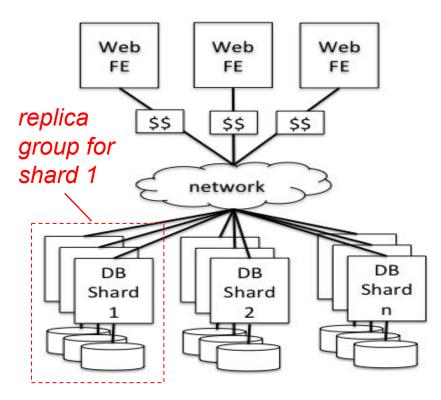
- FE and DB are both sharded:
 - FEs accept requests from end-users' browsers and process them concurrently.
 - DB is sharded, say by user IDs.
 - Suppose each DB backend is on its own transactional (ACID). Then, FE issues transactions against one or more DB shards.

Fault Tolerance: Replication



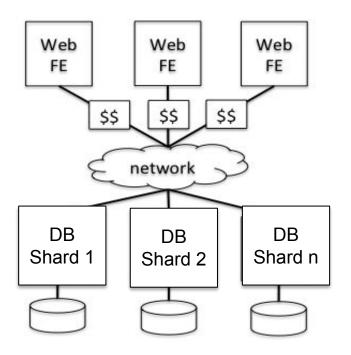
- FE is stateless, so the fact that it is shared means it's also replicated/fault tolerant.
- But DB is stateful, so active replication is needed for each shard. Each shard is managed by a *replica group*, which cooperate to keep themselves up to date with respect to the updates.
 FE sends requests for DB different shards go to different replica groups.

Challenges



Question: What are the challenges of implementing ACID across the entire **sharded & replicated**, DB **service**?

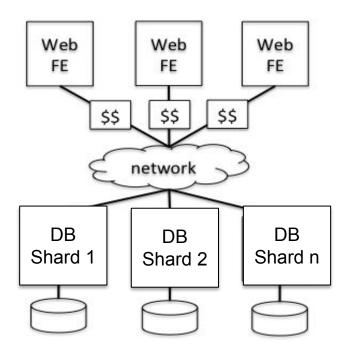
Challenges due to Sharding



- Ignore replication. Implementing ACID across all DB shard servers:
- Case 1: No transactions ever span multiple shards. Easy: individual DB shard performs transaction.
- Case 2: Transactions can span multiple shards. Challenge: shards participating on any transaction need to **agree** on (1) whether or not to commit a transaction and (2) when to release the locks.

Challenges due to Sharding (cont.)

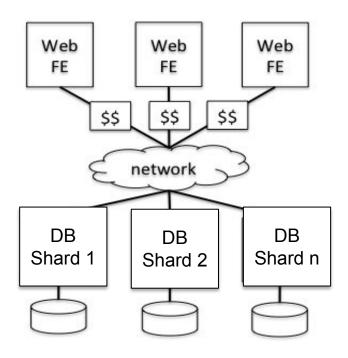
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Example:

- Say FE service is a banking service that supports the TRANSFER and REPORT_SUM functions from the previous lecture.
- If the two accounts are stored on different shards, then the two operations (deduct from one and add to the other) will need to be executed either both or neither.
- Unfortunately, the two machines can fail, or decide to unilaterally abort, *INDEPENDENTLY*.

Challenges due to Sharding (cont.)

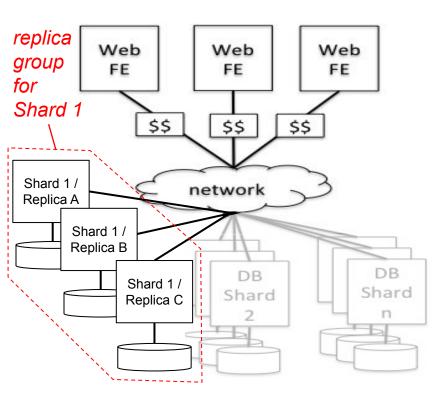


Example (continued):

- So, you need an agreement protocol, and in this case the most suitable is an atomic commitment protocol (why?).
- Well-known atomic commitment protocol: **two-phase commit**.

Challenges due to Replication

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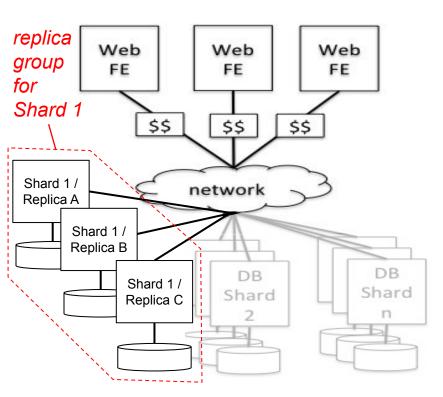


Ignore sharding. Implementing ACID across all replicas of a given shard:

- Challenge: All replicas of the shard must execute all operations in the same order.
- If the operations are deterministic, then agreeing on the order of keeps the copies of the database on the different replicas will evolve identically, i.e., they will all be kept consistent.

Challenges due to Replication (cont.)

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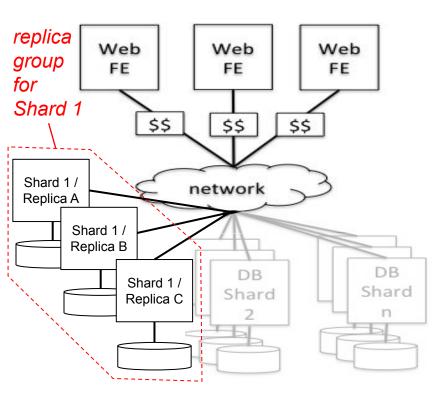


Example:

- Suppose there are two transactions, each with a single operation, against the same cell in the database:
 - TX1: x += 1
 - TX2: x *= 2
- Internally, all three replicas are ACID databases, so they will serialize these transactions, e.g., either (TX1, TX2) OR (TX2, TX1).
- If Replica A processes (TX1, TX2) and Replica B processes (TX2, TX1), then after executing these transactions, the DB copies on the two replicas will diverge to x=8 and x=7, respectively.

Challenges due to Replication (cont.)

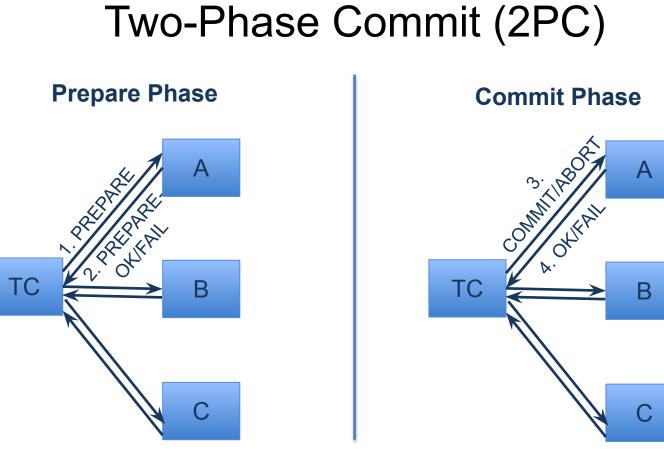
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Example (continued):

- The problem of agreement on the order in which to execute operations can be cast as an instance of the **consensus problem** (why?).
- Well known consensus protocol:
 Paxos.
- We study this protocol next time.

Two-Phase Commit (2PC)



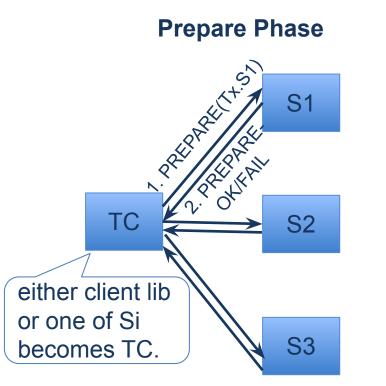
2PC for Distributed Transactions

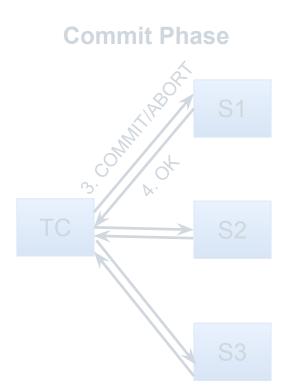
How 2PC integrates with WAL, 2PL that we studied for local transactions.

Here's a **rough** description of a client lib for distributed transactions:

- begin(): Client lib begin()'s a transaction on each separate shard. This produces a separate txID on each server (Tx.S1, Tx.S2...).
- As part of the distributed TX, the client sends the operation to the corresponding shard server. Say op1 goes to S1, op2 goes to S2. Each server grabs local locks, adds op to their local WAL.
- **abort():** Client sends the ABORT message to S1, S2,

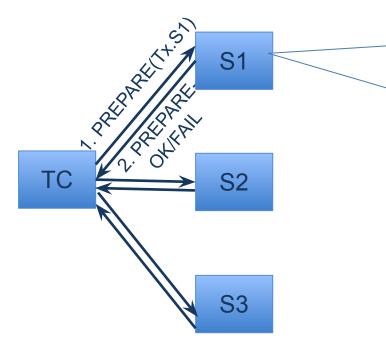
2PC commit()





2PC commit()

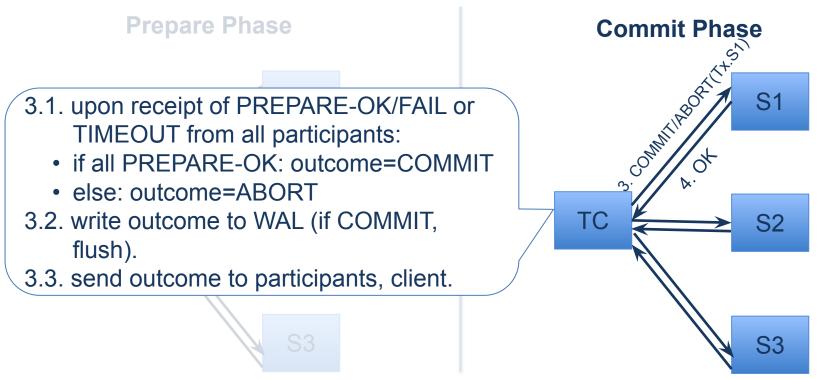
Prepare Phase



Commit Phase

(while holding locks for Tx.S1)
2.1. can commit transaction Tx.S1?
2.2. write PREPAE-OK/FAIL to WAL.
2.3. send PREPARE-OK/FAIL to TC.
2.4. wait to hear response from TC.
(continue holding locks for Tx.S1)

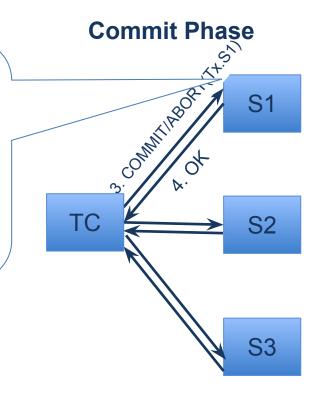
2PC commit()

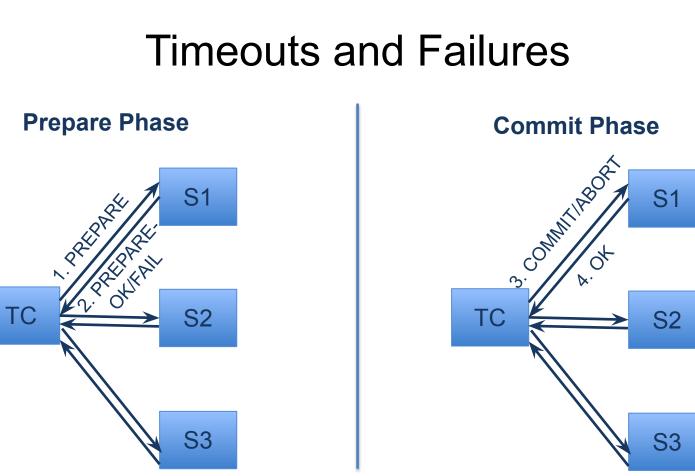


2PC commit()

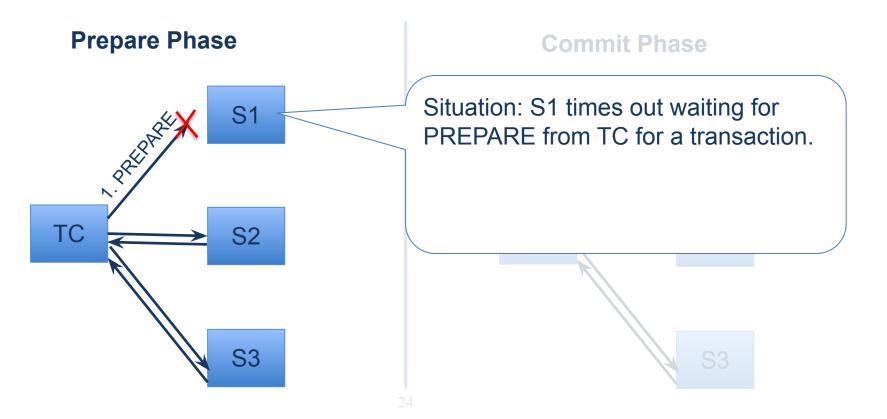
Prepare Phase

(recall S1 is holding locks for Tx.S1)
4.1. enter COMMIT/ABORT in its WAL (if COMMIT, also flush).
4.2. if ABORT, revert Tx.S1 using WAL.
4.3. release all locks for Tx.S1.
4.4. send OK to TC (who will keep retrying to send outcome to participants until it has OK from all).



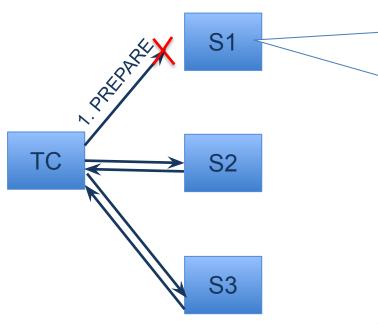






Timeouts

Prepare Phase

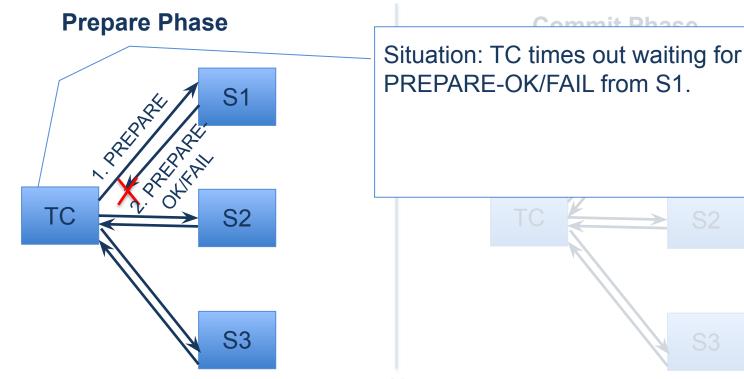


Commit Phase

Situation: S1 times out waiting for PREPARE from TC for a transaction.

Action: Safe for S1 to unilaterally **abort()**.

Timeouts



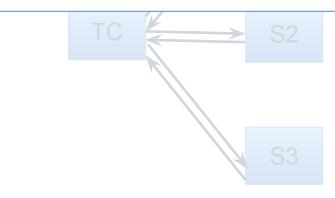
Timeouts

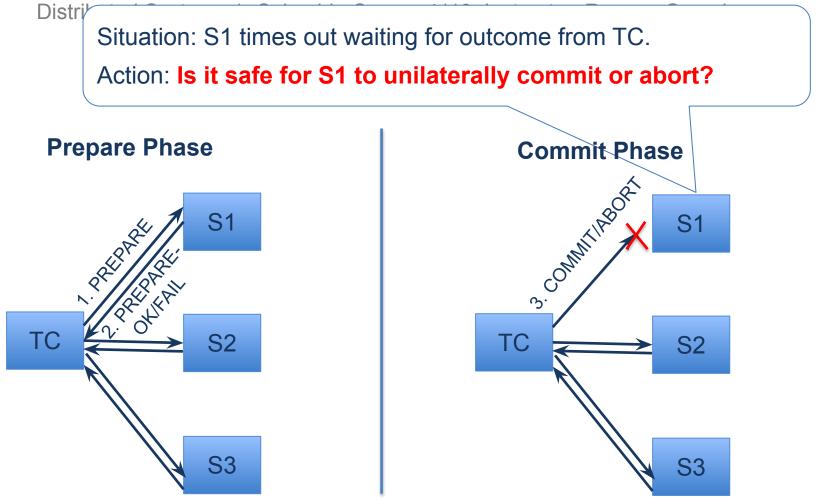
Prepare Phase S1 TC S2 **S**3

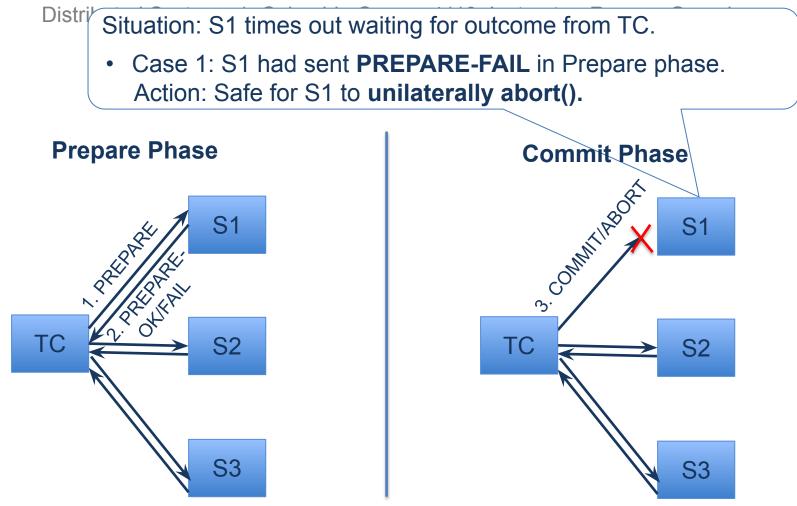
Commit Dhaco

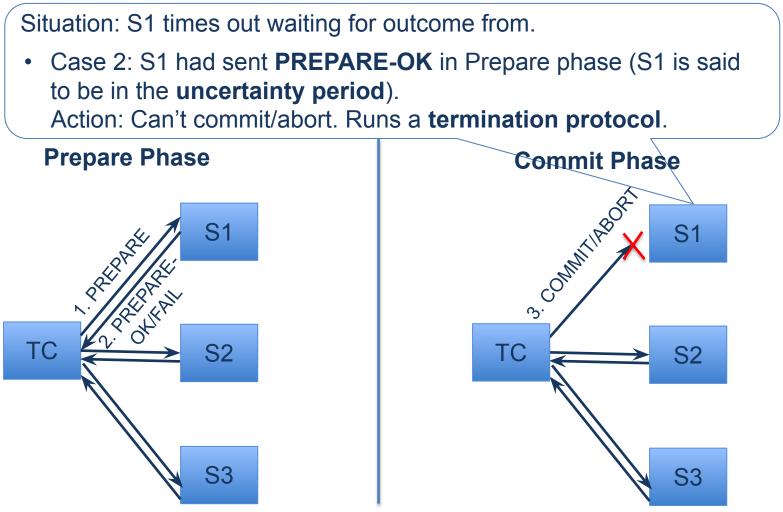
Situation: TC times out waiting for PREPARE-OK/FAIL from S1.

Action: Safe for TC to initiate distributed **abort()** by sending ABORT outcome.



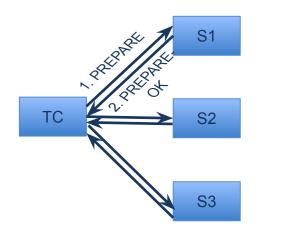


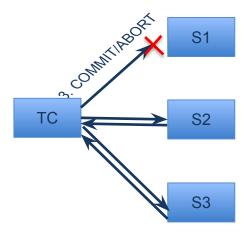




Termination Protocol

- Wait for TC to come back (might take a while and recall Si hold locks!).
- Could also ask other participants whether they got outcome.
 - If one did, they can all terminate the protocol accordingly.
 - If none did (e.g., TC died or got partitioned right before it sent outcome), then participants are **BLOCKED** till TC comes back.





Failures

- Similar analysis applies for failures.
- Some cases:
 - if participant is not in uncertainty period, on recovery, can decide what to do (unilaterally abort if no decision, otherwise do what decision is.)
 - if participant is in uncertainty period, it cannot decide on its own, must invoke the termination protocol (which, as before, may not actually terminate if TC fails).

2PC Limitations

2PC is Blocking

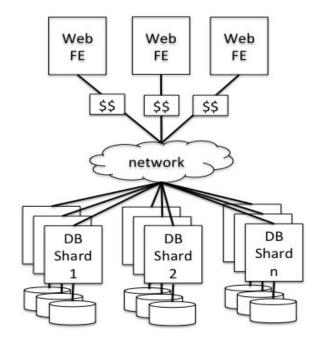
- A process can block indefinitely in its uncertainty period until a TC or network failure is resolved.
- If TC is also a participant, then a single-site failure can cause 2PC to block indefinitely!
- And it blocks while each shard server is holding locks, preventing other transactions that don't even interact with the failed shard server from making progress!
- This is why 2PC is called a **blocking protocol** and *cannot* be used as a basis for fault tolerance.

2PC is Expensive

- Time complexity: 3 message latencies on the critical path: PREPARE \rightarrow PREPARE-OK/FAIL \rightarrow ABORT/COMMIT.
- Message complexity: common case for n participants + 1 TC: 3n messages.
- That's expensive, esp. if shards are geo distributed.
- Optimizations, or adding an extra phase (3PC), cannot address the blocking/performance problems of 2PC while maintaining its semantic.

Next Time

- Start talking about how to achieve fault tolerance through replication.
- Unlike in sharded DBs, the problems that arise in a replicated DB can be cast as **consensus**.
- We will discuss **Paxos**, the best known consensus protocol.
- So we'll finally know, at least in principle, how to construct our fuller Web service architecture from Lecture 1 (took us long, ha?).



Key Papers

• [Lampson-Sturgis-1979] Butler Lampson and Howard Sturgis. Crash Recovery in a Distributed Data Storage System. In Distributed Systems— Architecture and Implementation, 1979.